

The Digital Revolution: Machines That Make

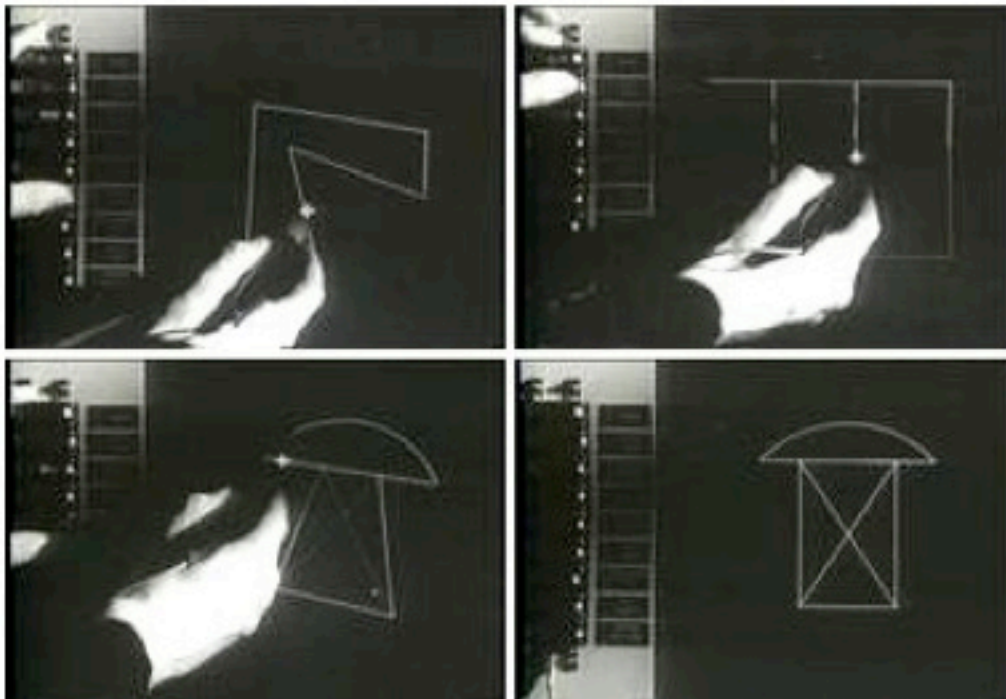
Ilan Moyer – CTMTM Co-Founder
Natan Linder – MIT Media Lab



Agenda

- Digital FAB Overview
- CBA MTM Project
- How make something with MTMs

From CNC to FABLAB



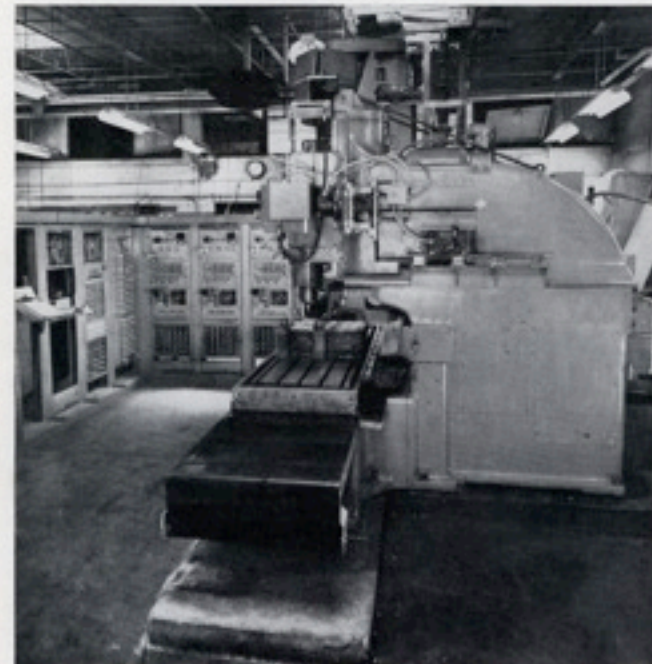
Ivan Sutherland, 1963
Sketchpad

the job. After one effort he reported in disappointment that in his cylinder of 14-inch diameter "of the worst place the long diameter exceeded the short by three-eighths of an inch," but in 1776 Watt's partner, Matthew Boulton, was able to write: "Mr. Wilkinson has bored several cylinders almost without error, that of 50 inches diameter, which we have put up at Tipton, does not see the thickness of an old shilling in any part." The importance of Wilkinson's boring machine cannot be overes-

timated. It made the steam engine a commercial success, and it was the harbinger of all the large, accurate metal-working tools of modern industry. Another productive Englishman of the same period was Joseph Bramah. His inventions included one of the most successful locks ever devised, the hydraulic press, various wood-working machines, the four-way valve, a beer pump and the water closet. To manufacture his inventions he and an associate, Henry Maudslay, created several metal-

cutting machines. The most significant of these was a screw-cutting lathe with a slide rest and change gears scarcely like our modern lathes.

THE NEXT great step forward in machine technology was pioneered by Eli Whitney. Although he is remembered mainly as the inventor of the cotton gin, his greatest contribution was an innovation of much more general import: interchangeability of manufactured parts. In 1796 Whitney, her-



MACHINE AND CONTROL are shown here in entirety. For details of the control panels (left) see pages 104 and 105. The machine has universal motions: the "head" holding the cutting tool, moves vertically; the "cross

slide" moves the head back and forth across table; the table moves from side to side under tool. The control system coordinates all these motions simultaneously to perform the operations shown on the opposite page.

William Pease, 1950
"Card-a-matic Milling Machine"

Fab Labs



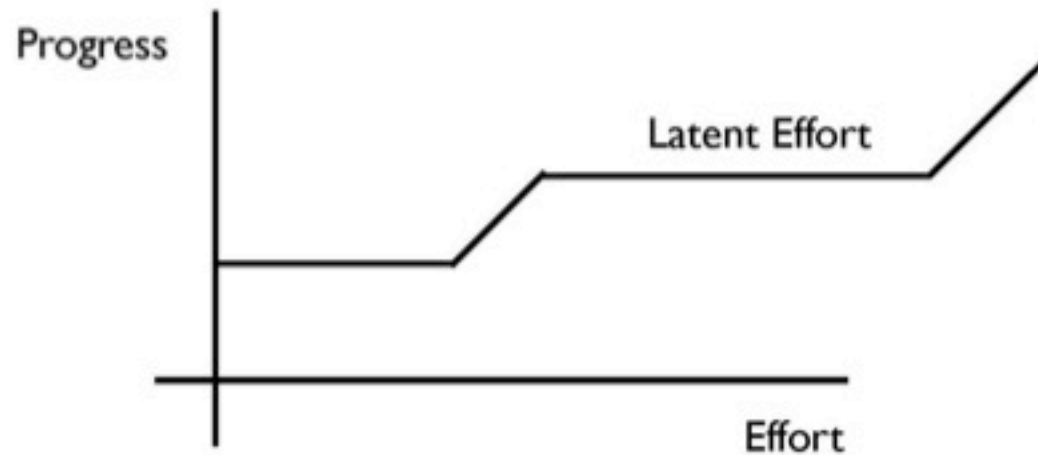
*fabrication and
instrumentation divide*



Rapid prototyping?

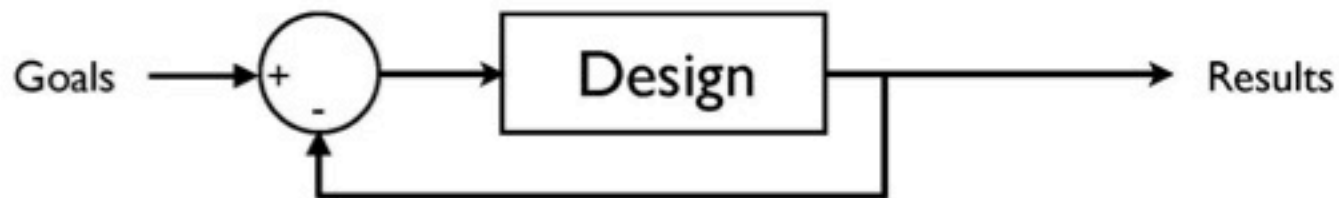
- Rapid prototyping (industrial design)
- Scalability (parametric designs)
- Object (or manufacturing) for one person

Rapid prototyping?

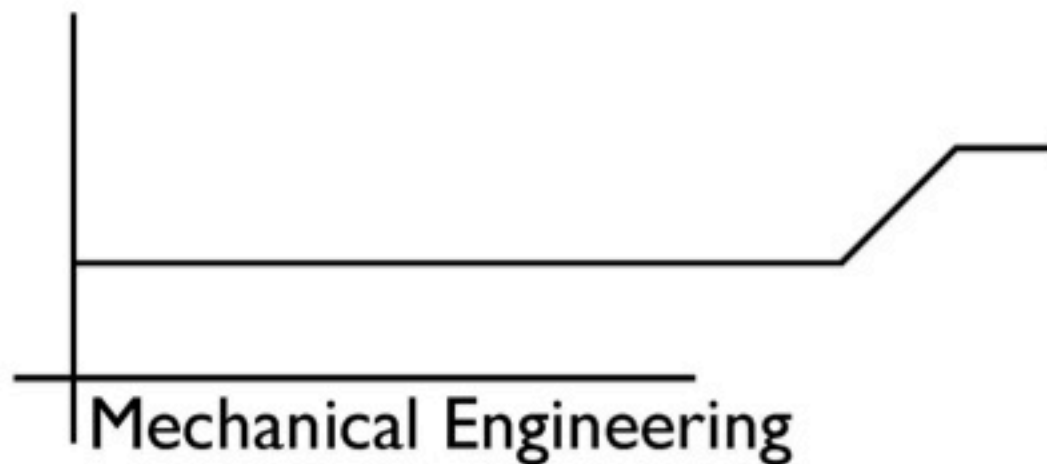
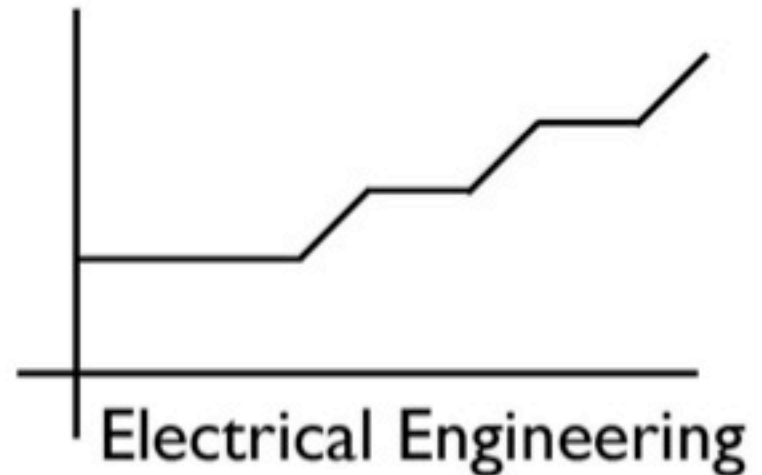
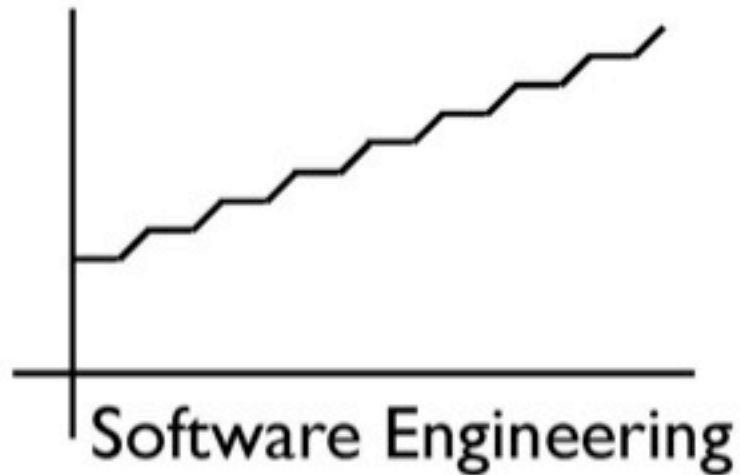


Progress is a state change.

Rapid Prototyping is closed loop.



Rapid prototyping?



Techniques

Additive



Subtractive



Subtractive



Waterjet



Milling Machine



Beam Laser Cutter



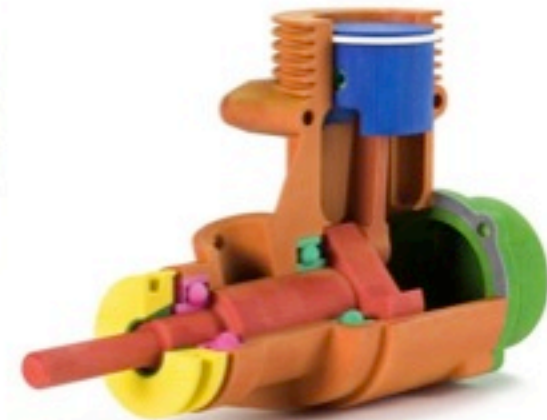
Plasma Cutter

Additive

- **Selective laser sintering (SLS):**
Thermoplastics, metals, sand
- **Fused Deposition Modeling (FDM):**
Thermoplastics
- **Stereolithography (SL):** Photopolymer
- Electron Beam Melting (EBM): Titanium alloys
- 3D Ceramic Printing:
Various clay and ceramic materials



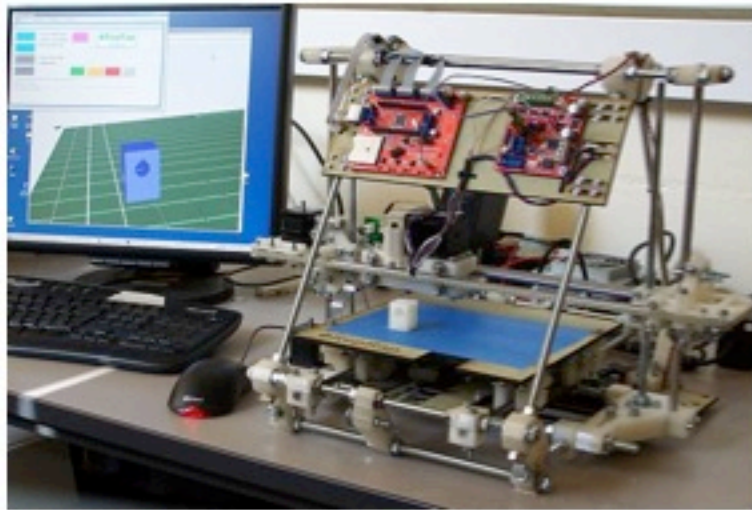
ZCOPP



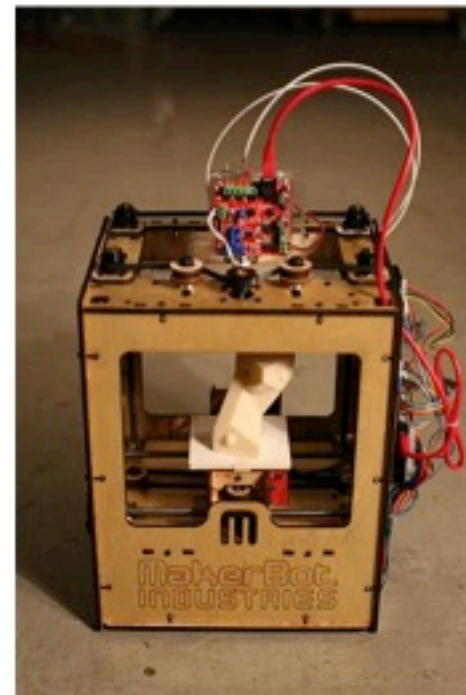
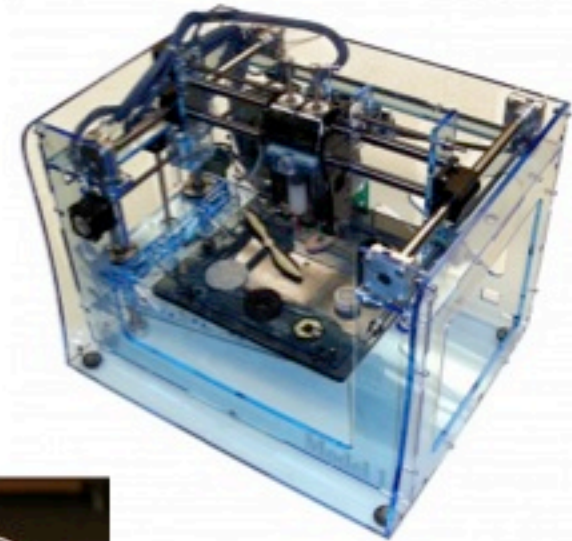
Dimension



Personal Fabrication & DIY

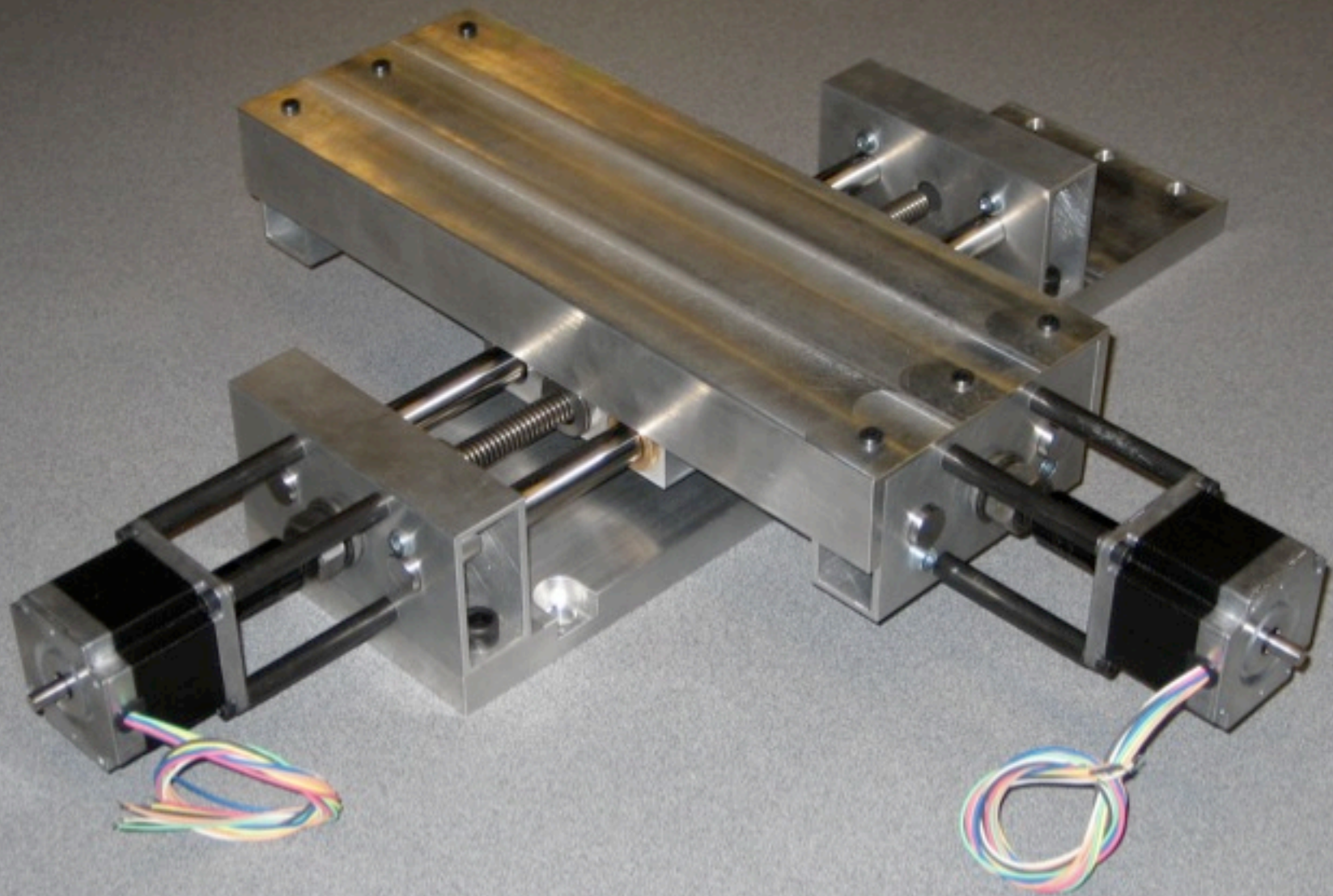


RepRap

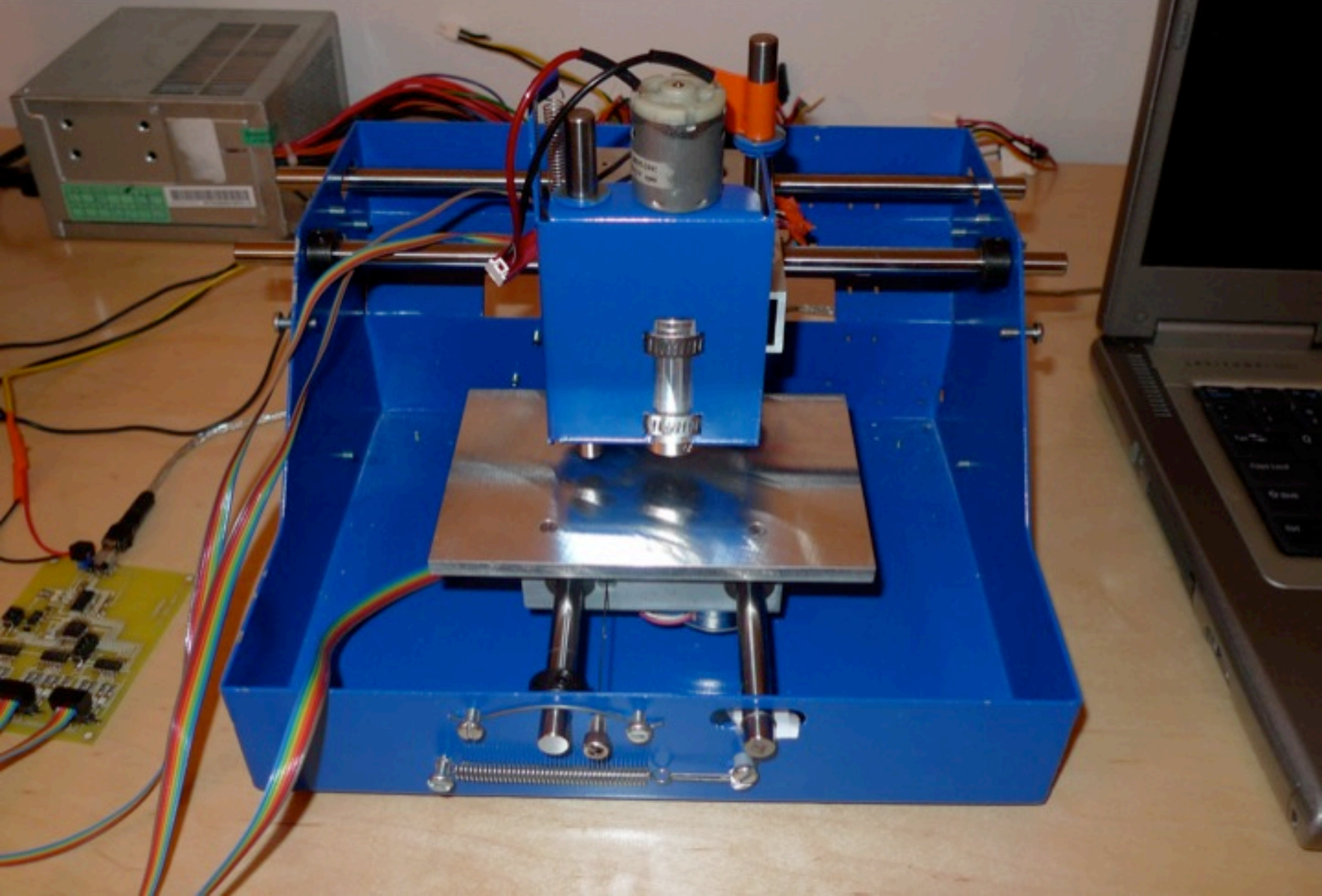


MakerBot
INDUSTRIES

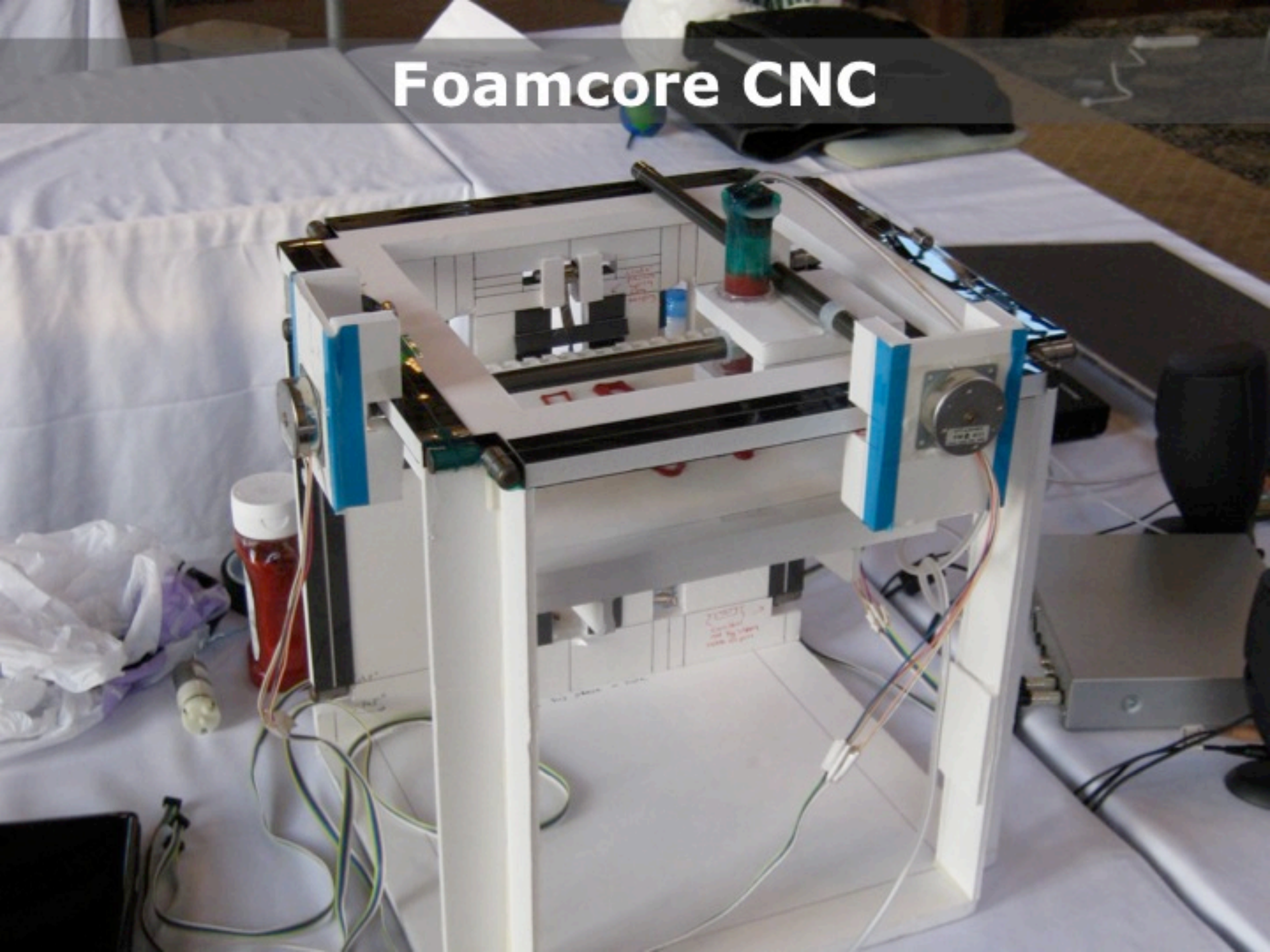
Parametric XY Stage



PCB Mill



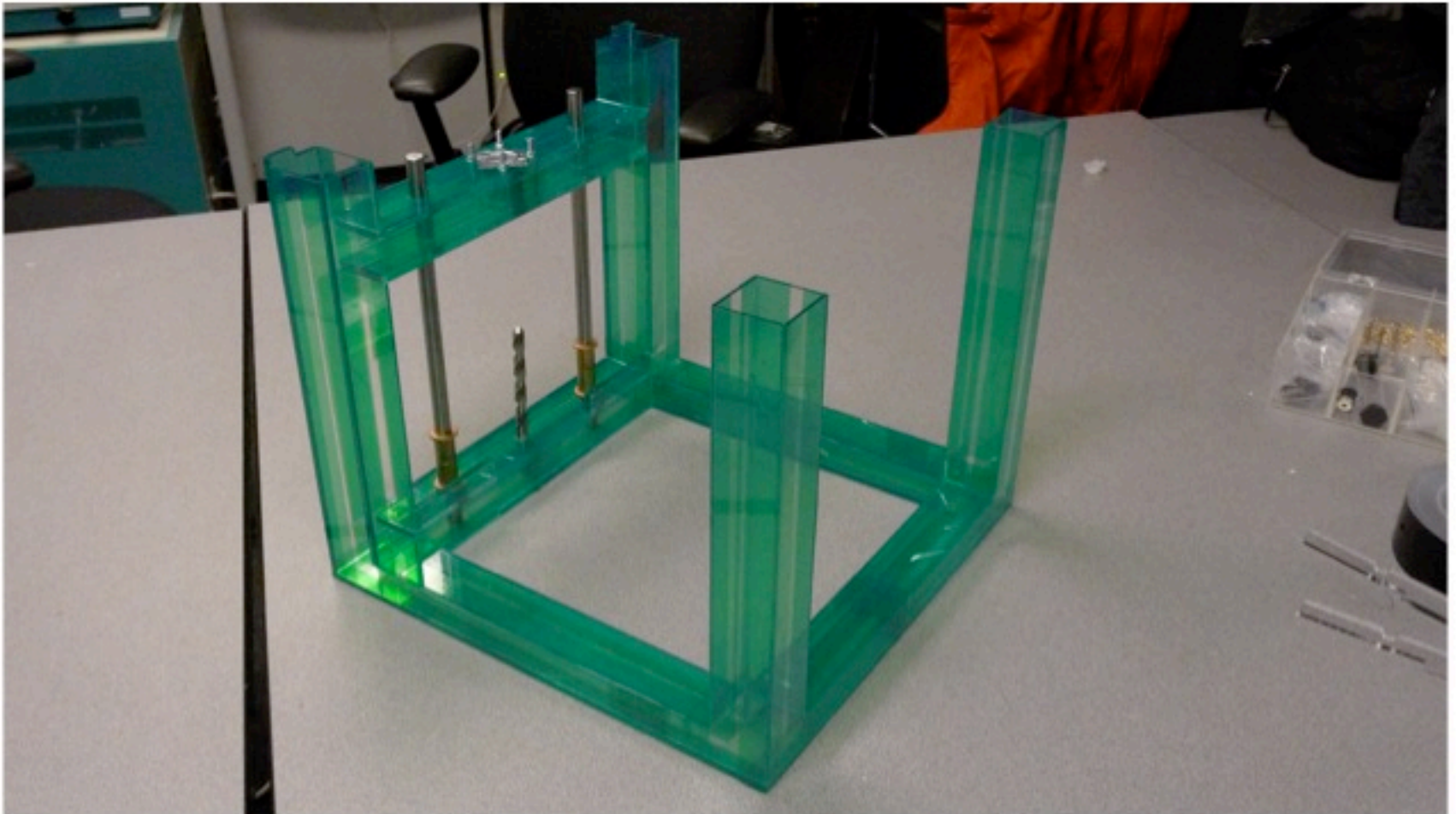
Foamcore CNC

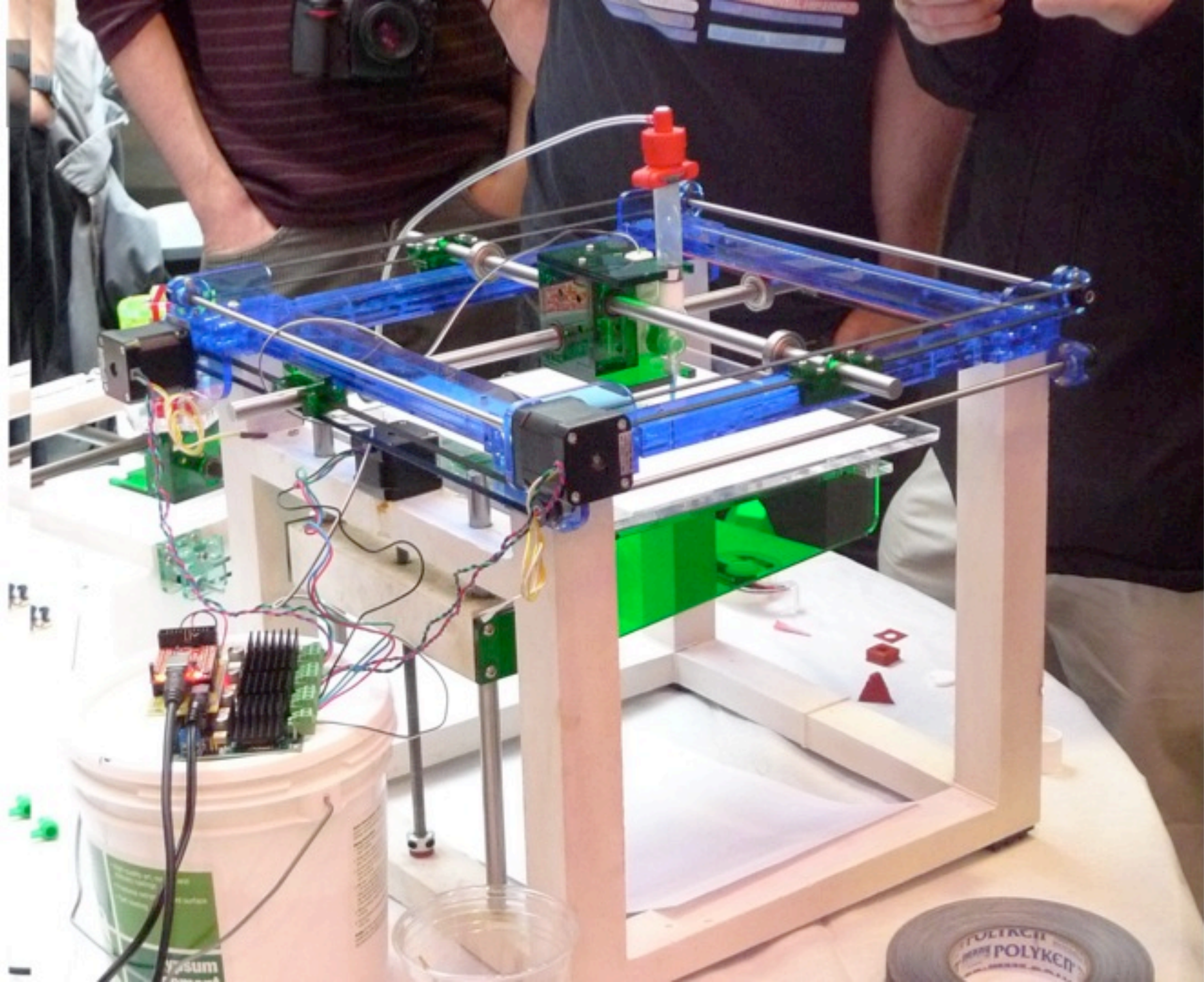


Plaster Disaster



Plaster Disaster





Made in India



machines that make

themselves • other machines • functional parts • fun stuff

MACHINES

MtM A-Z



DIY Vinyl Cutter



\$100 Mantis CNC Mill



TOOLHEADS

Spindle



Low Cost Spindle



CONTROL

Virtual Machines



Internet Zero



Simple Stepper



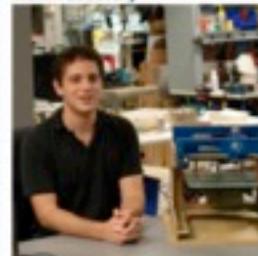
Modular Binary Stepper Driver

PEOPLE

Jonathan Ward



Maxim Lobovsky

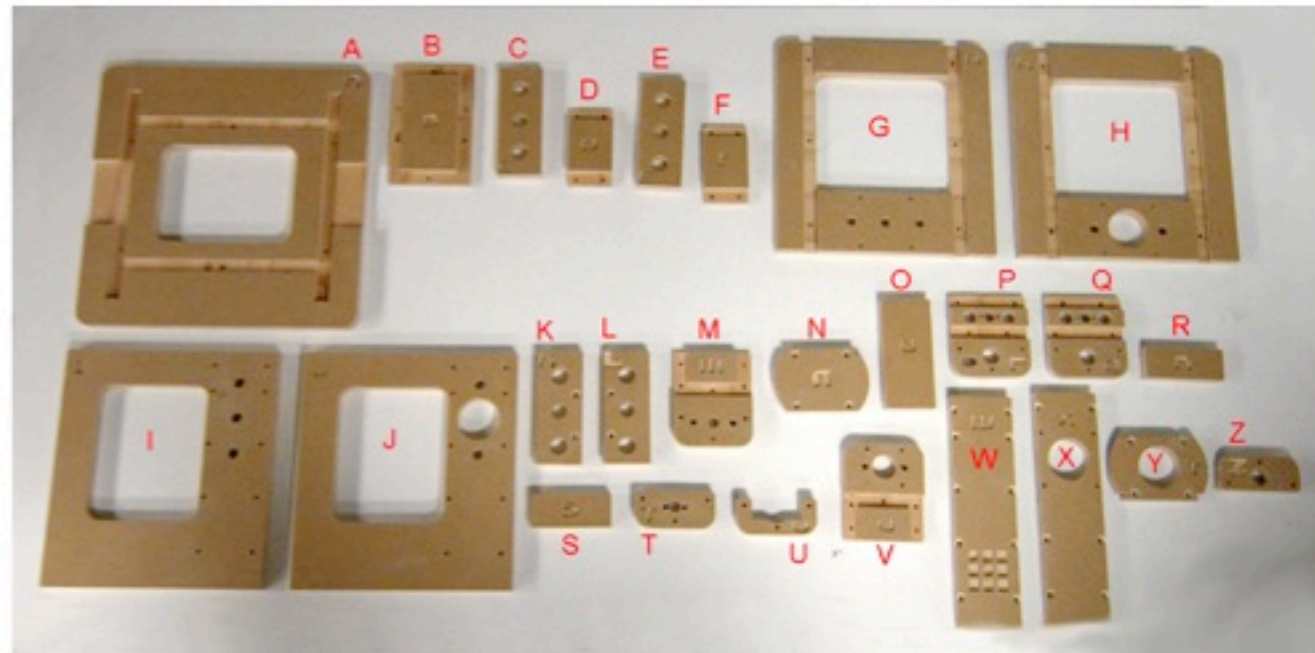
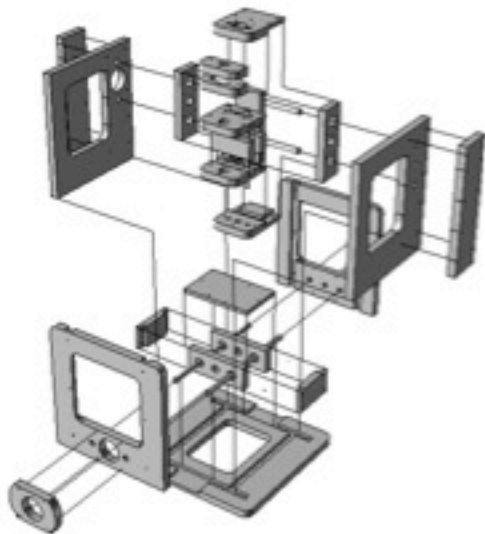
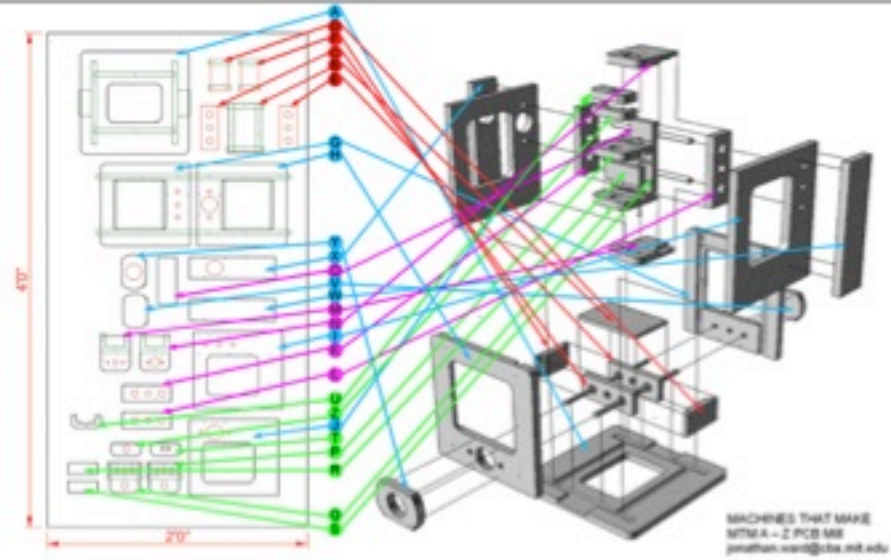
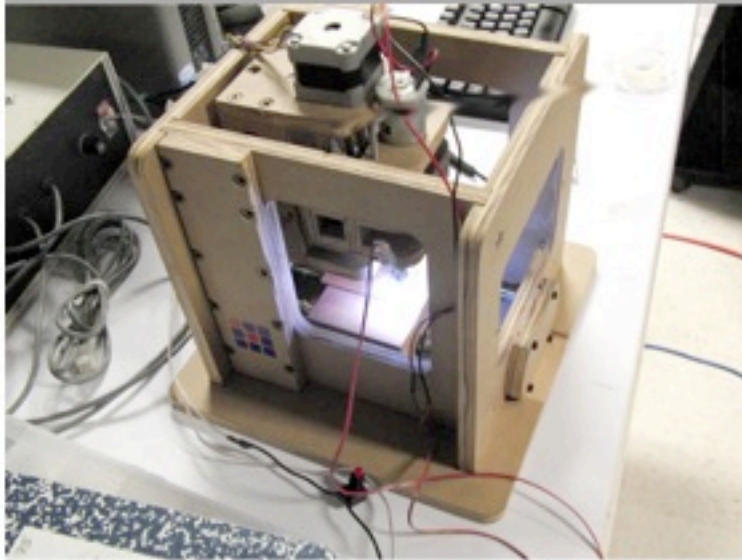


Steffen Reichert

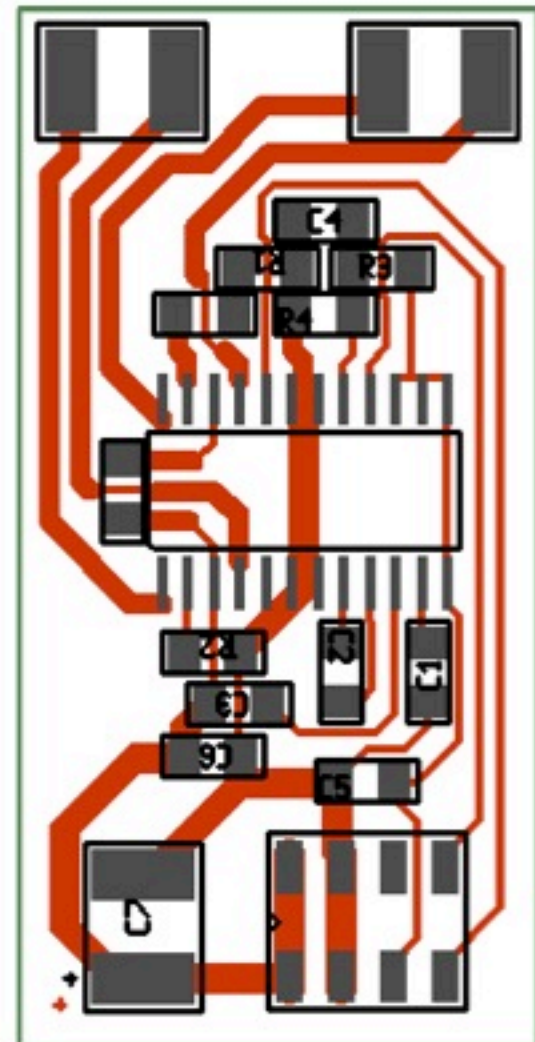
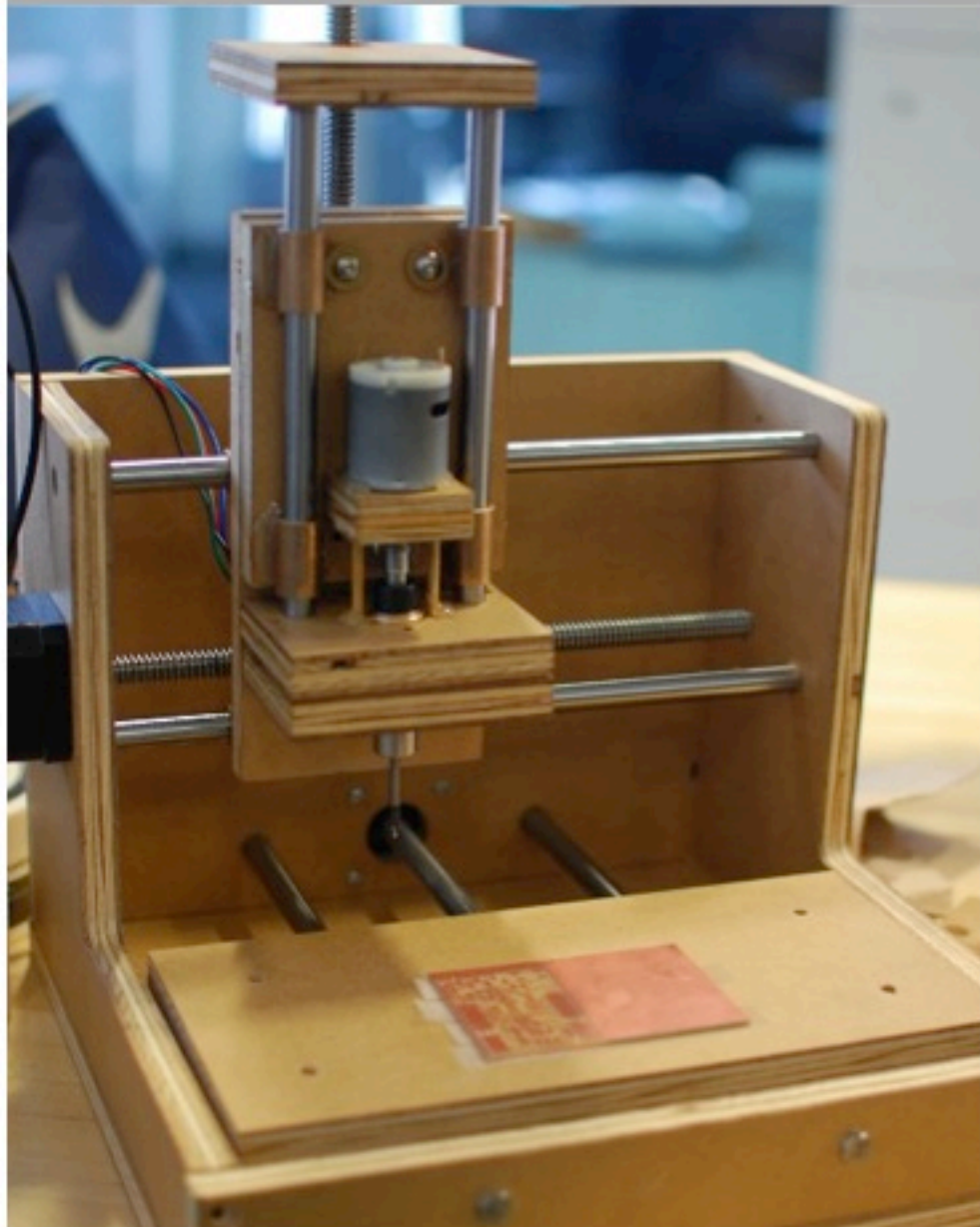
MTM

- Multifab machines – multi-functions
- Open source
- Networked
- Low cost
- Exploring different materials and form factors

MTM AZ – Jonathan Ward



Mantis < \$100 ! – David Carr



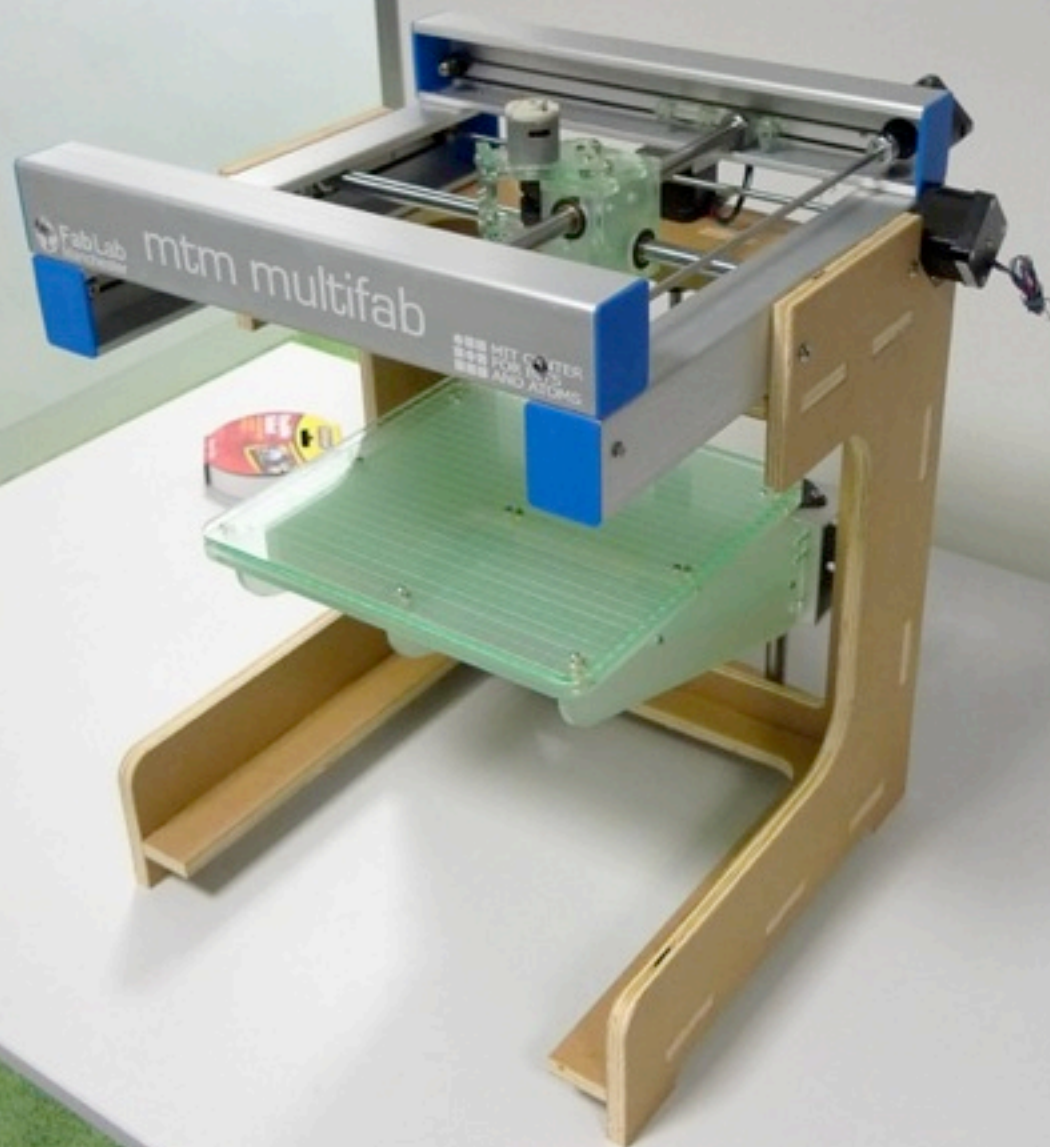
<http://makeyourbot.org/>

Casting & Molding – David Carr

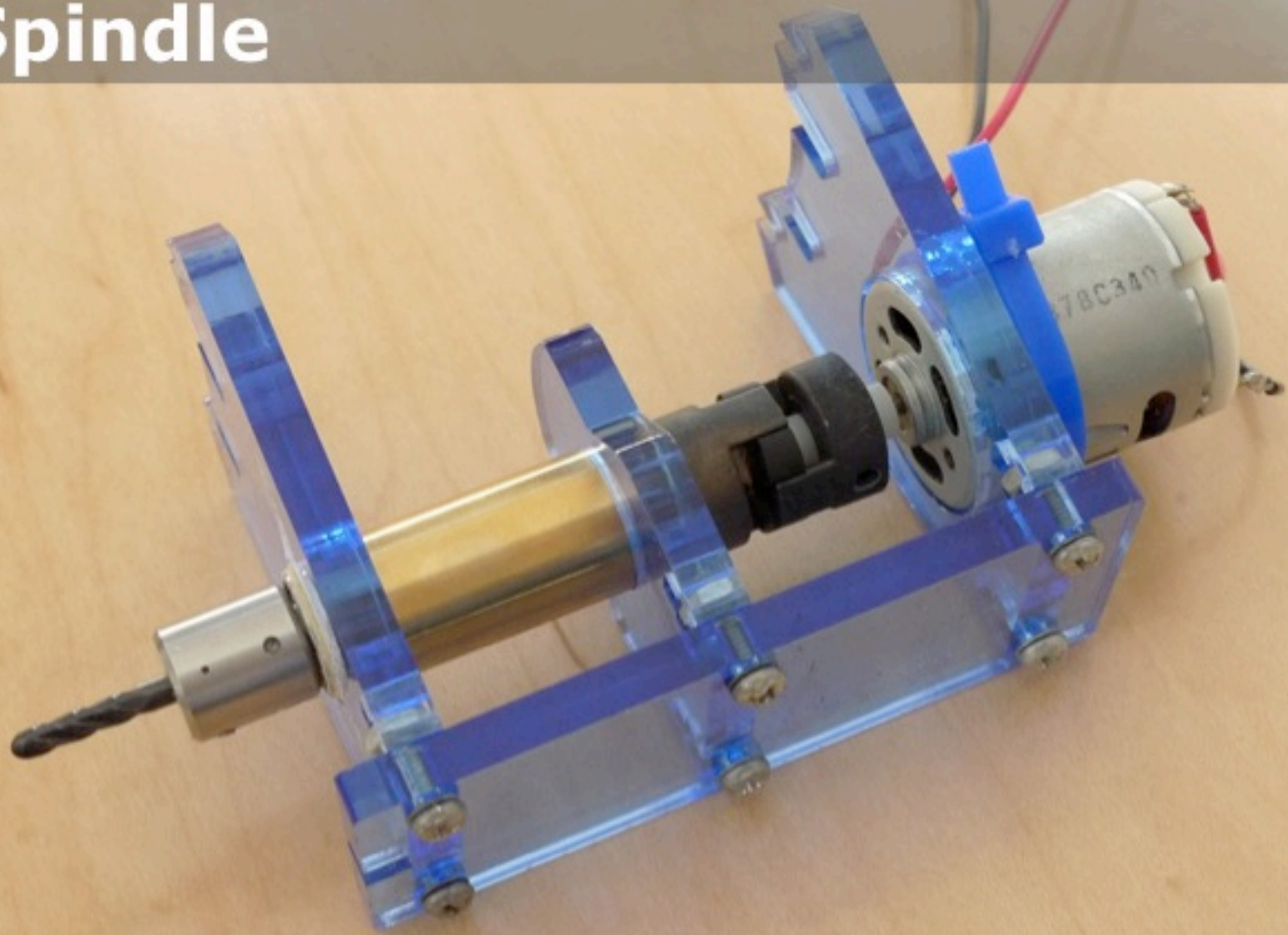




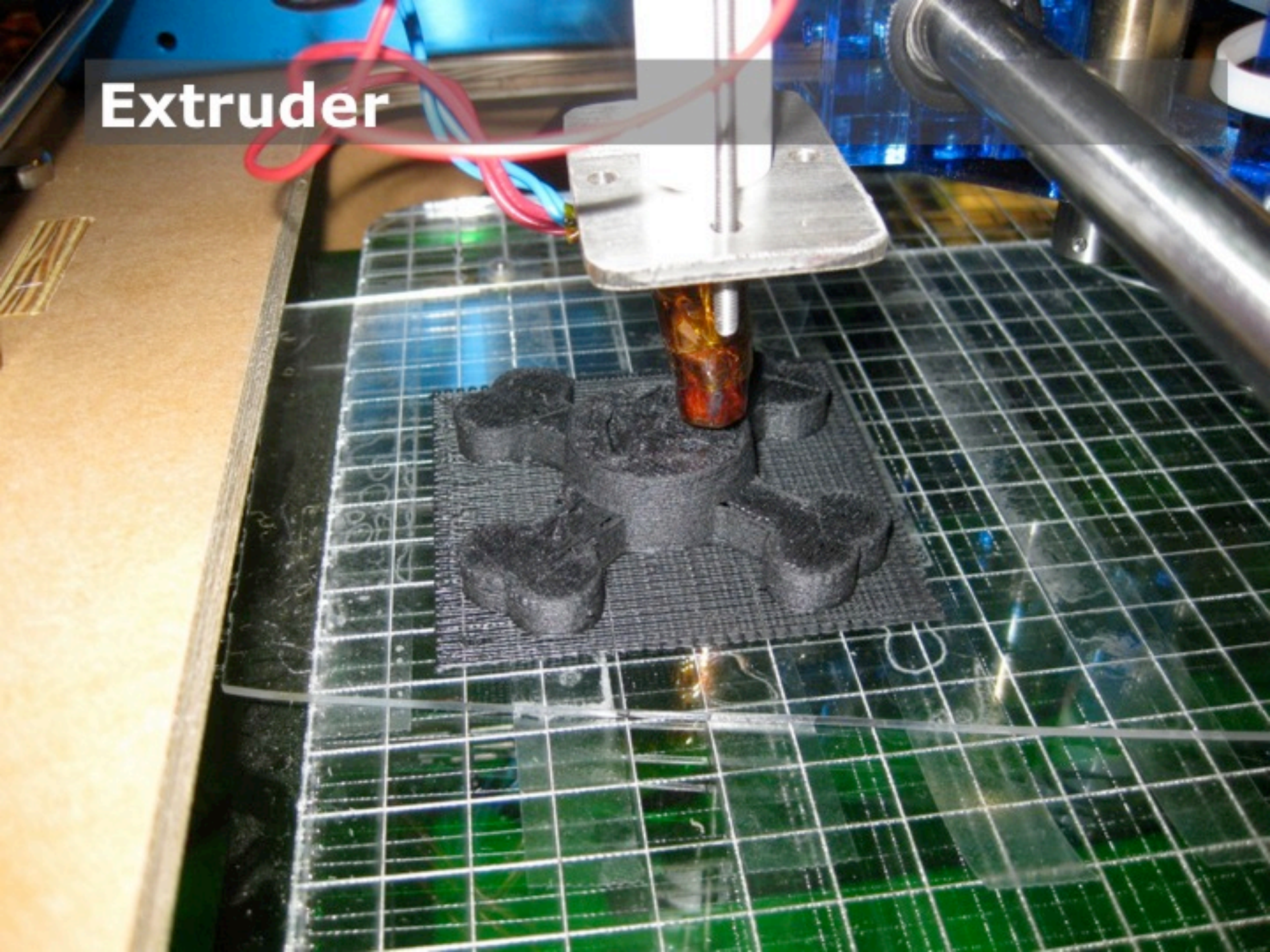
MTM Multifab – Ilan Moyer



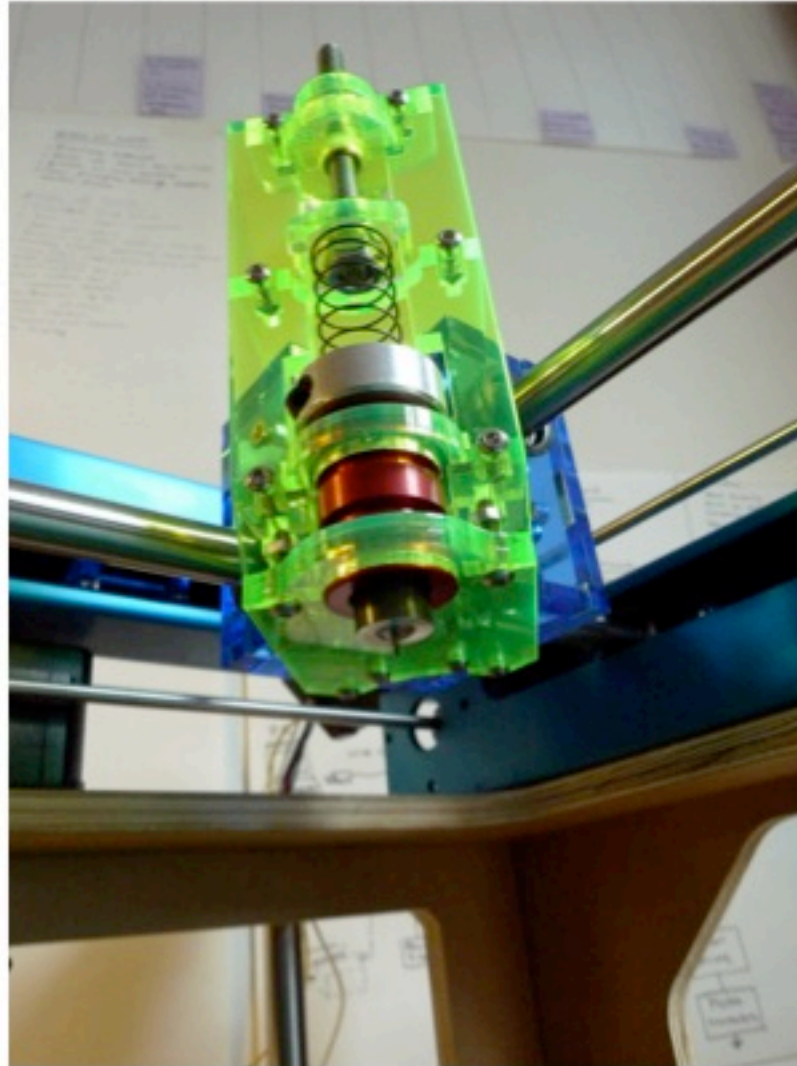
Spindle



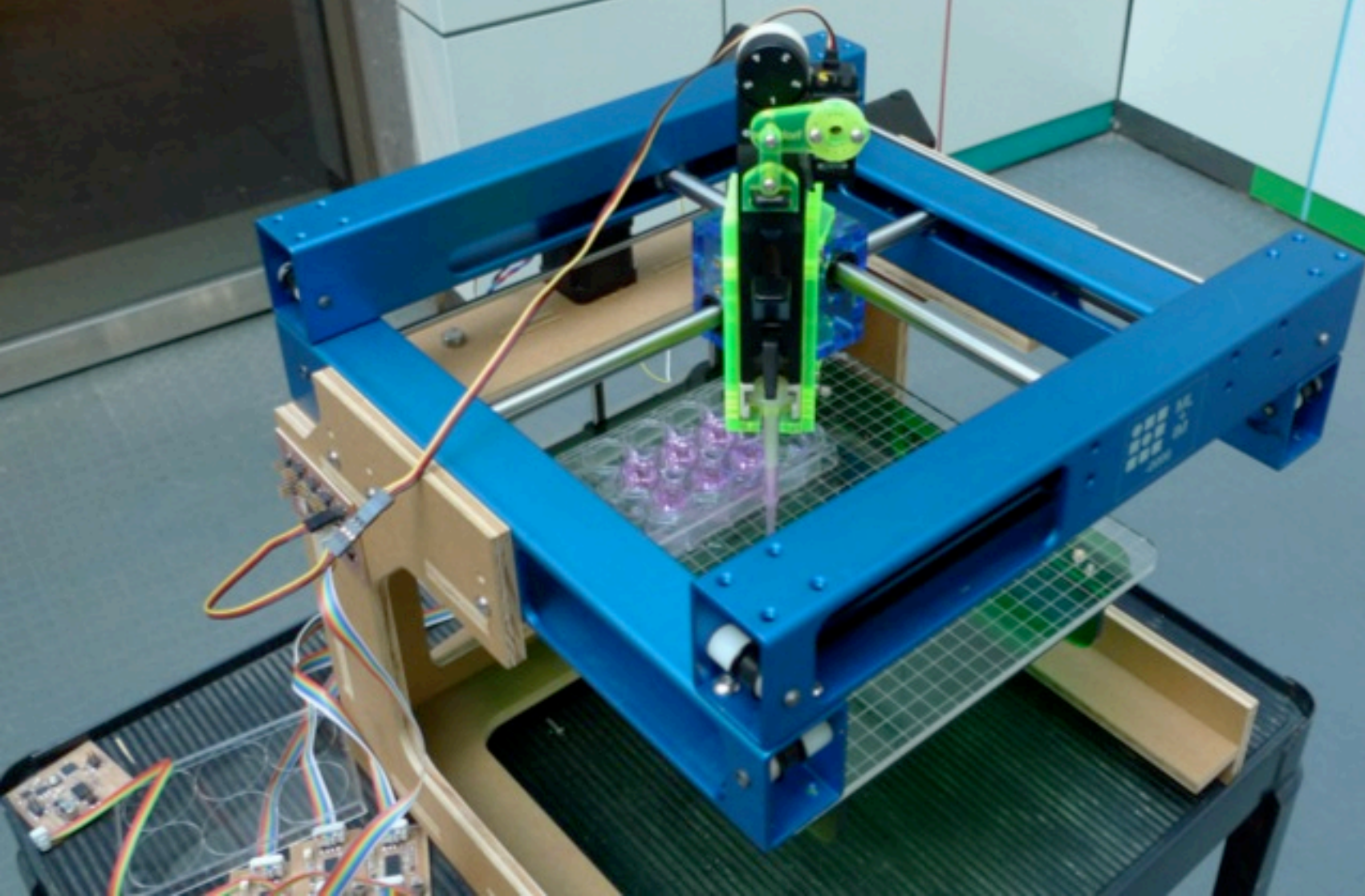
Extruder



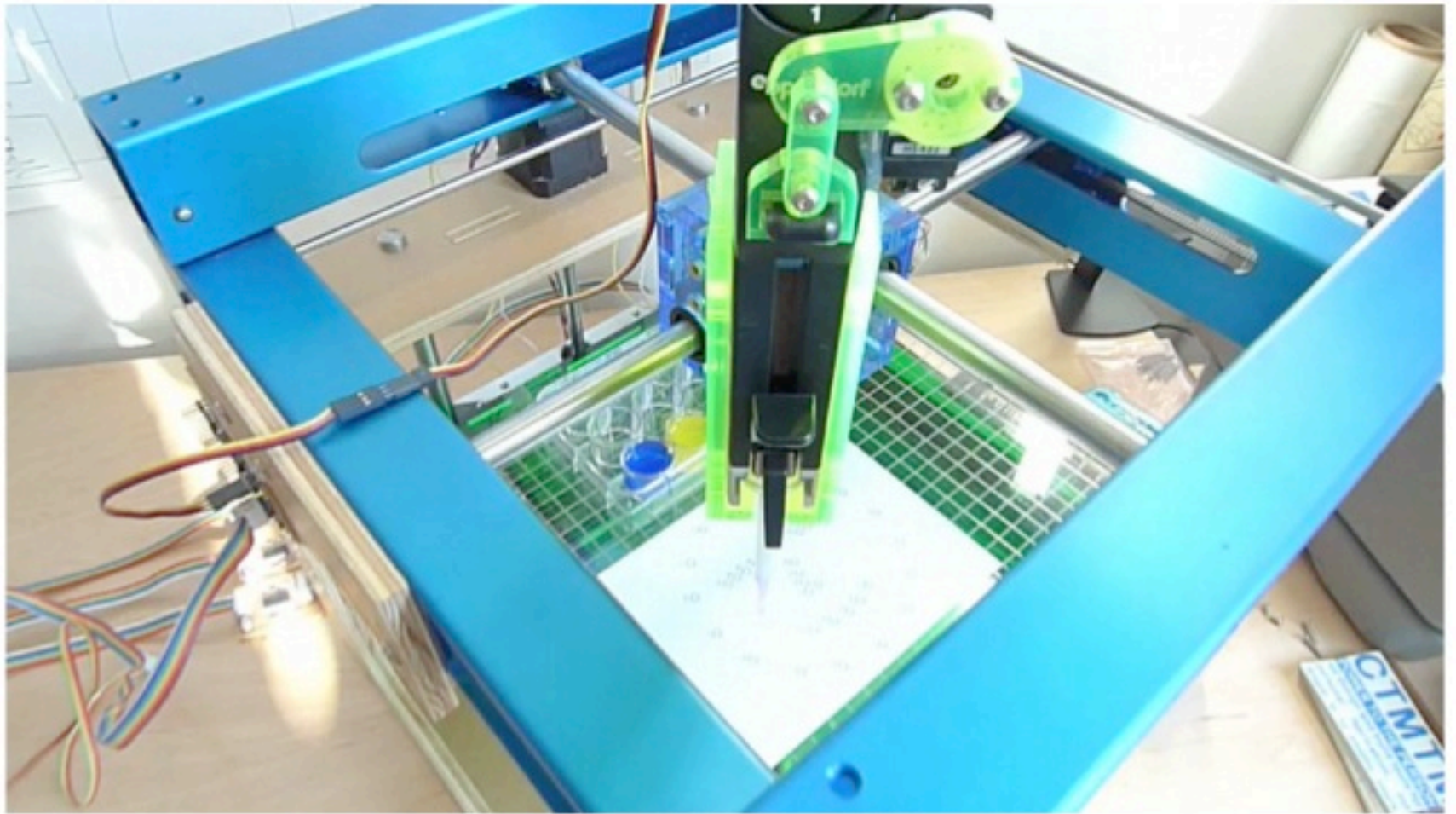
Vinyl Cutter



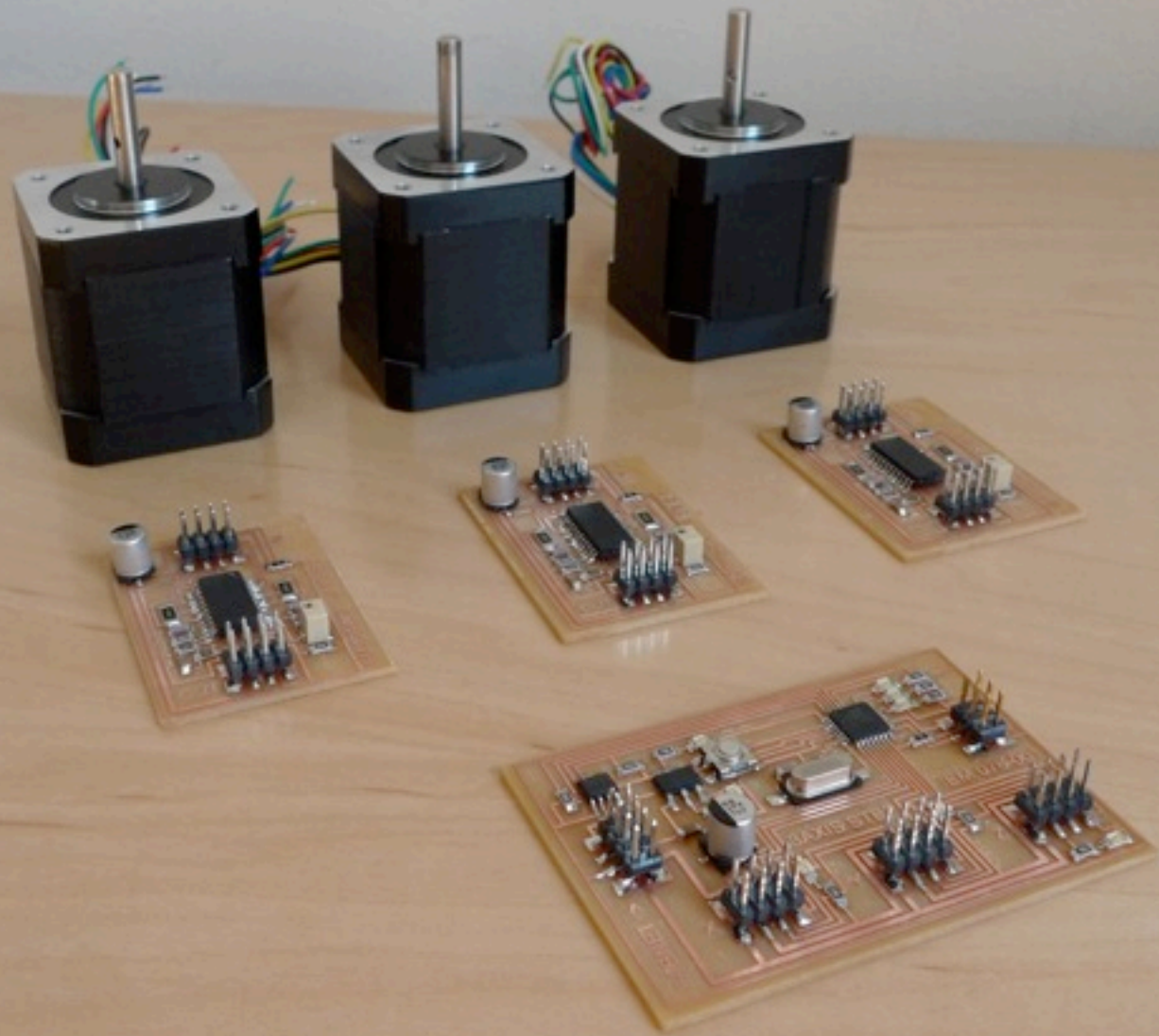
Auto-Pipetter



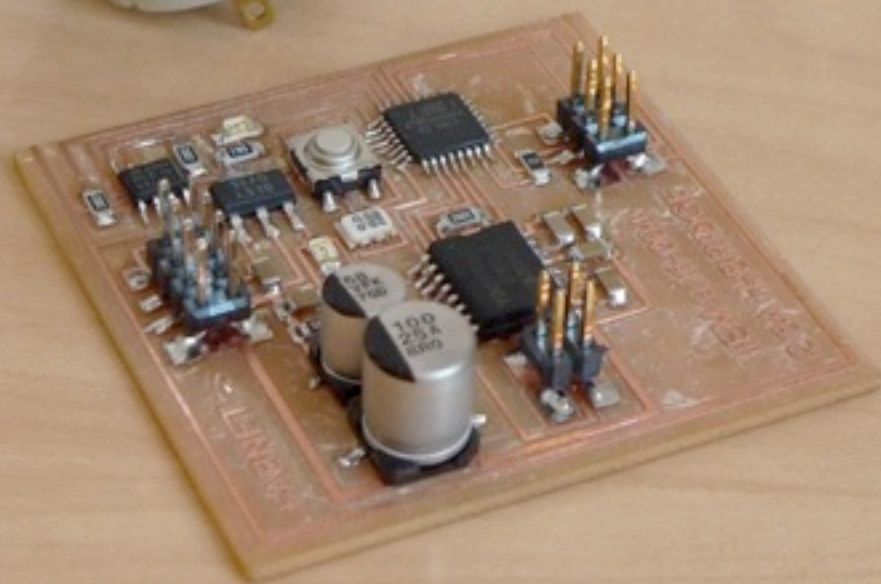
Auto-Pipetter



Networked motor control



Spindle control



Virtual Machines Control

```
apmmpcbborder.py - /Users/Fuzz/mtm/people/jilan/VM/vm10/apmmpcbborder.py
mtm.machine_position = [float(0), float(0), float(0)]
mtm.initialize_debug("apmmpcbborder.py")
traverse_speed = 30
retract_speed = 2.0
cutting_speed = 10
plunge_speed = 2.0
z_down = -0.08
z_up = 0.05
mtm.spindle_on(1)
mtm.backlash_compensation_on()
for i in range(3):

    z_down = -0.08*(float(i+1)/3.0)

    mtm.move( z = z_up, rate = retract_speed)
    mtm.move(0.175,1.618, z_up, traverse_speed)
    mtm.move( z = z_down, rate = plunge_speed)
    mtm.open_group(0)
    mtm.move(0.866,1.618, z_down, cutting_speed)
    mtm.move(0.868,1.616, z_down, cutting_speed)
    mtm.move(0.88,1.616, z_down, cutting_speed)
    mtm.move(0.882,1.614, z_down, cutting_speed)
    mtm.move(0.888,1.614, z_down, cutting_speed)
    mtm.move(0.891,1.612, z_down, cutting_speed)
    mtm.move(0.897,1.612, z_down, cutting_speed)
    mtm.move(0.899,1.61, z_down, cutting_speed)
    mtm.move(0.905,1.61, z_down, cutting_speed)
    mtm.move(0.907,1.608, z_down, cutting_speed)
    mtm.move(0.911,1.608, z_down, cutting_speed)
    mtm.move(0.913,1.606, z_down, cutting_speed)
    mtm.move(0.921,1.604, z_down, cutting_speed)
    mtm.move(0.923,1.602, z_down, cutting_speed)
    mtm.move(0.929,1.6, z_down, cutting_speed)
    mtm.move(0.931,1.598, z_down, cutting_speed)
    mtm.move(0.937,1.596, z_down, cutting_speed)
    mtm.move(0.939,1.594, z_down, cutting_speed)
    mtm.move(0.945,1.592, z_down, cutting_speed)
    mtm.move(0.947,1.59, z_down, cutting_speed)
    mtm.move(0.954,1.588, z_down, cutting_speed)
    mtm.move(0.958,1.583, z_down, cutting_speed)
```

Ln: 1, Col: 0

VIRTUAL MACHINE ENVIRONMENT 10 - REV. A2

----- MACHINE COMPONENTS -----

mtm():

| | | |
|-----------------------------------|----------------------|---------|
| --> XYZ Driver is LAUREL TRI-AXIS | @ 192. 168. 233. 146 | require |
| --> Spindle is LAUREL TRI-AXIS | @ 192. 168. 166. 80 | require |
| --> Trunnion is GENERIC VMO | @ ? . ? . ? . ? | quire |

-----EXECUTE SINGLE COMMAND-----

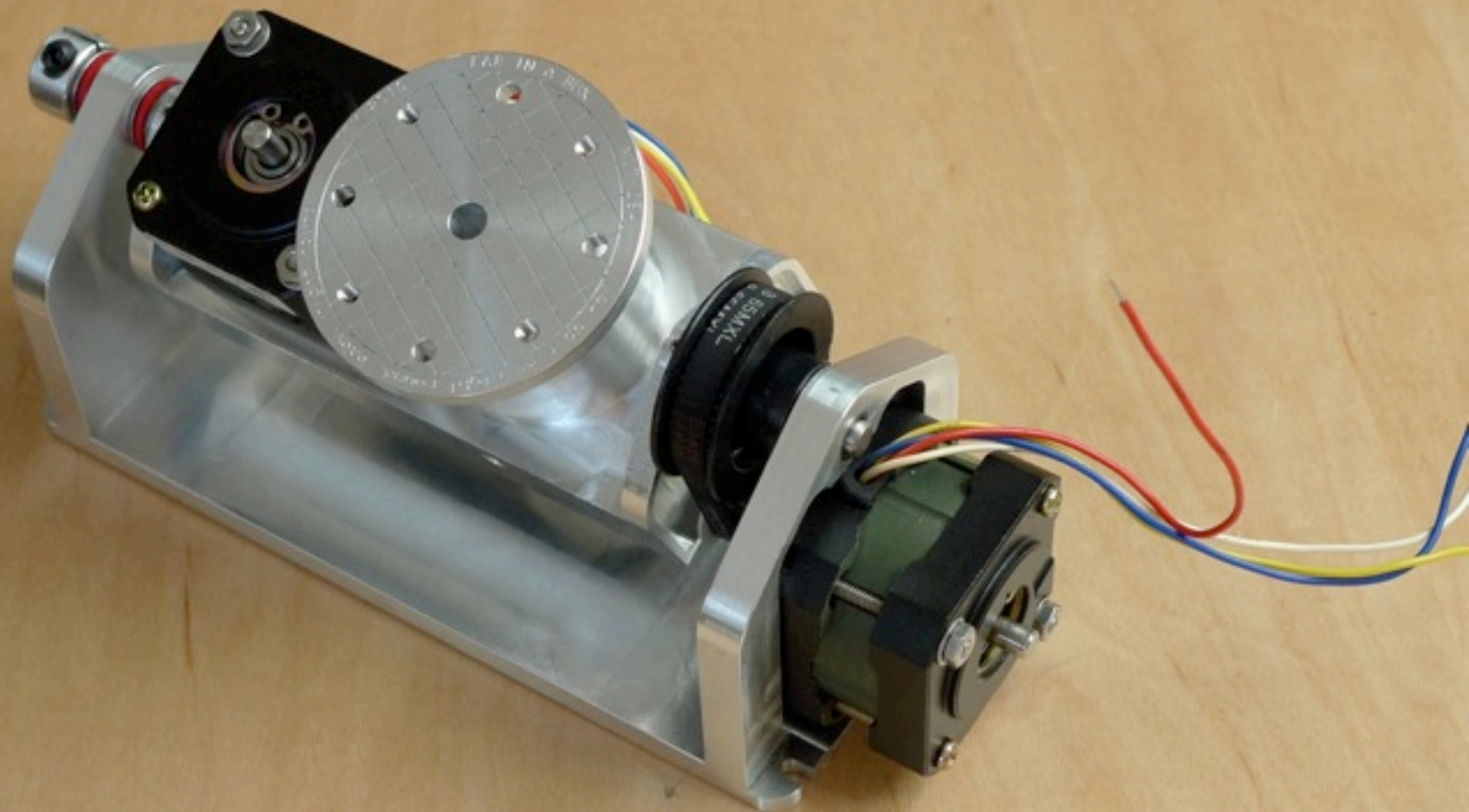
COMMAND:

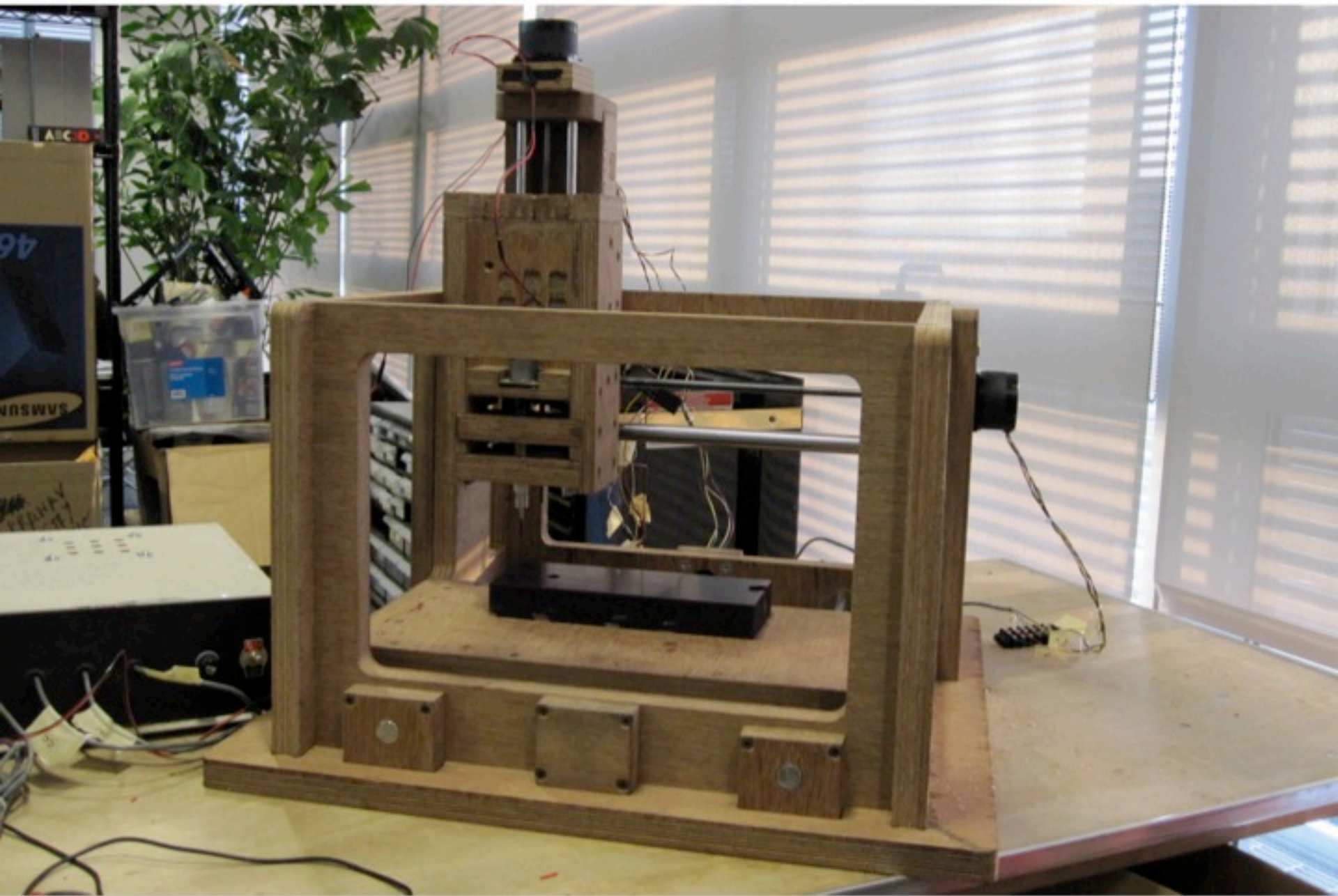
-----LOAD AND RUN VMC FILE-----

FILE:

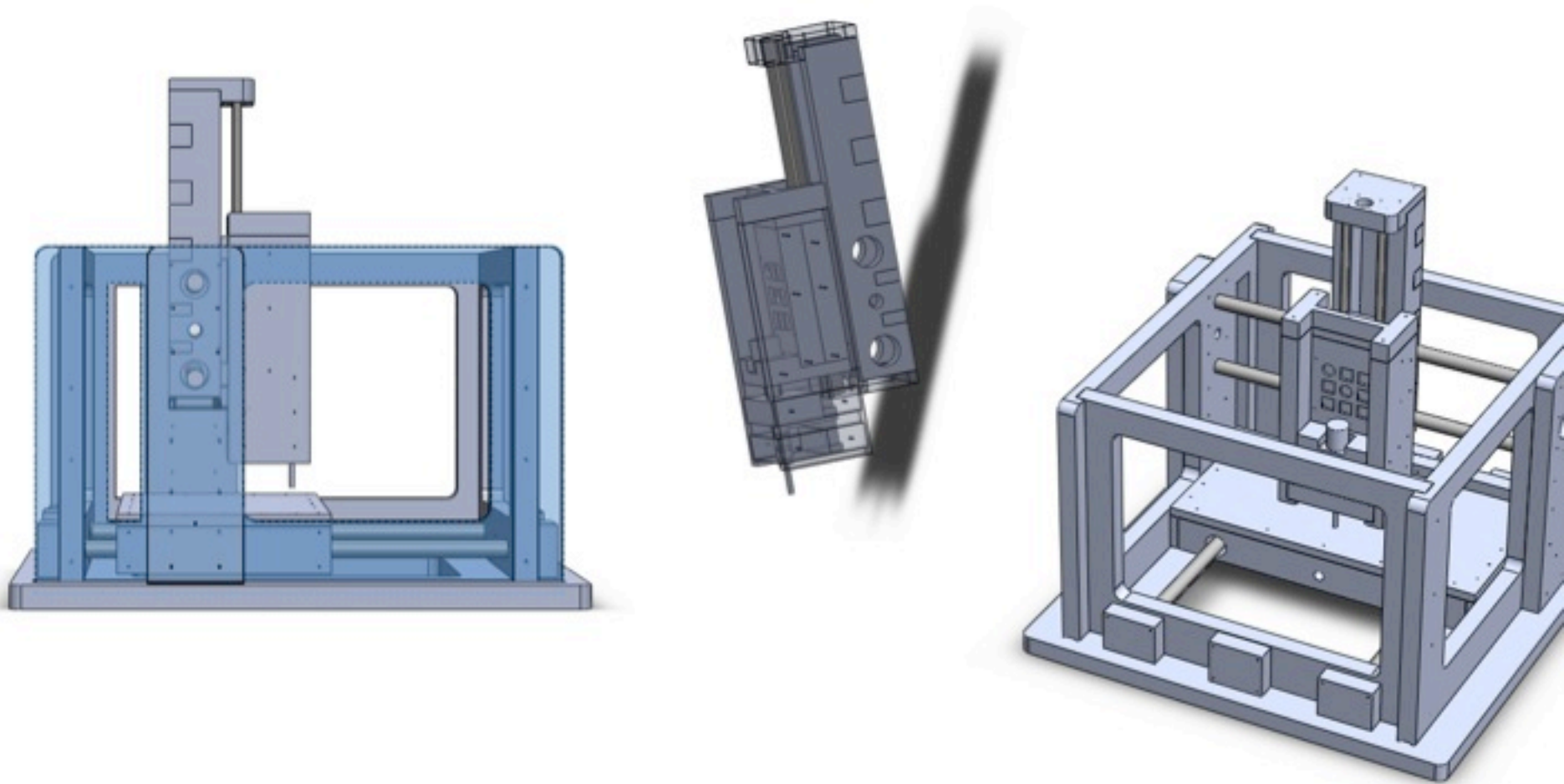
CURRENT LINE: mtm.spindle_on(0)

5 Axis Trunnion



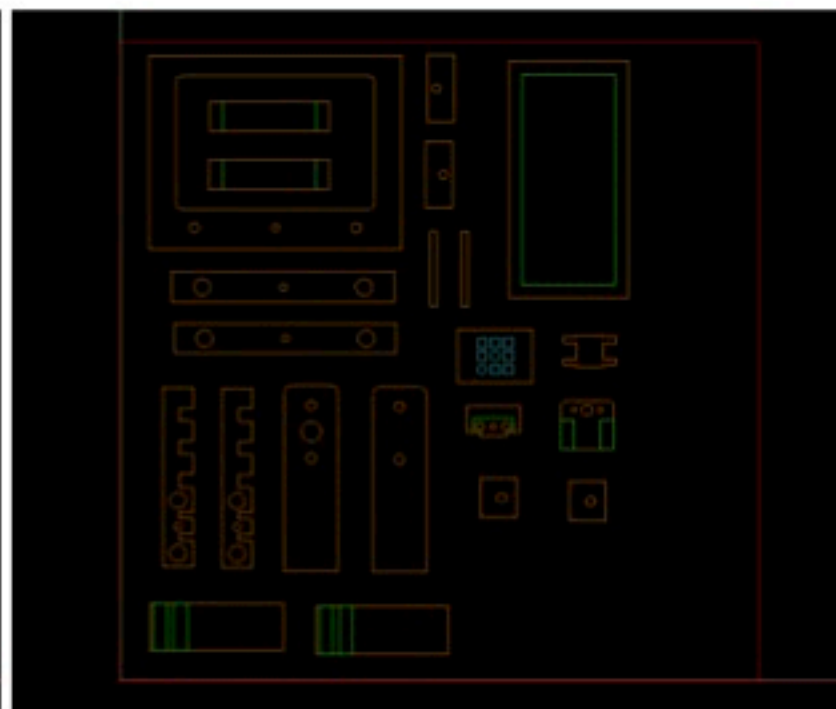
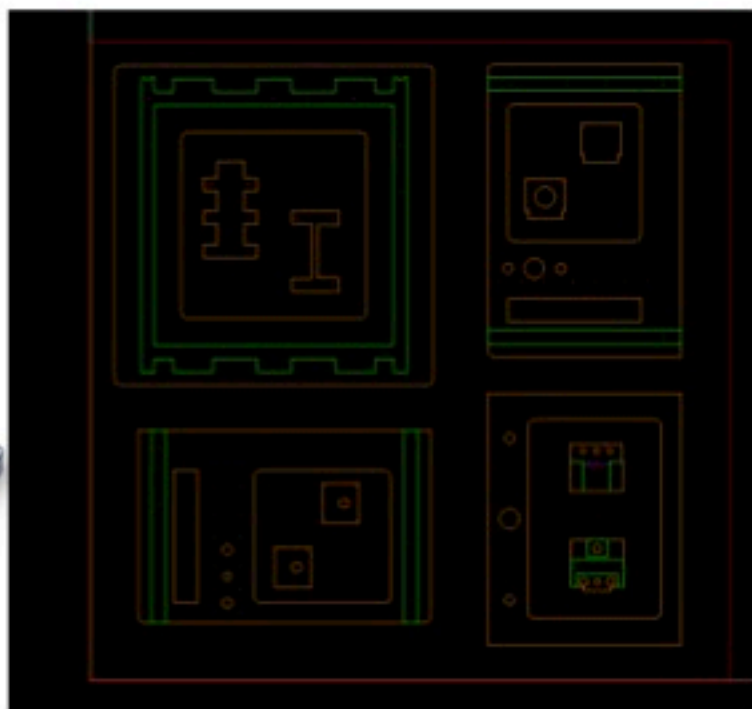
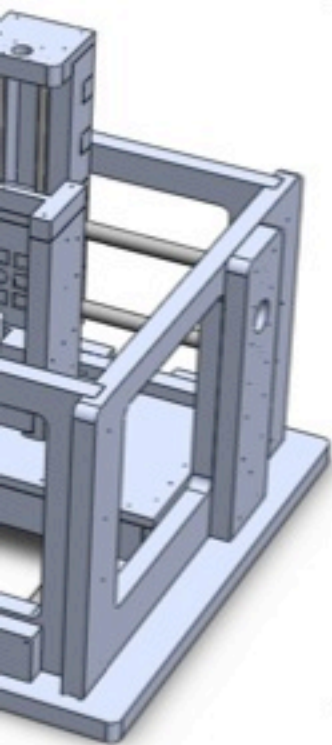


MTM Little John



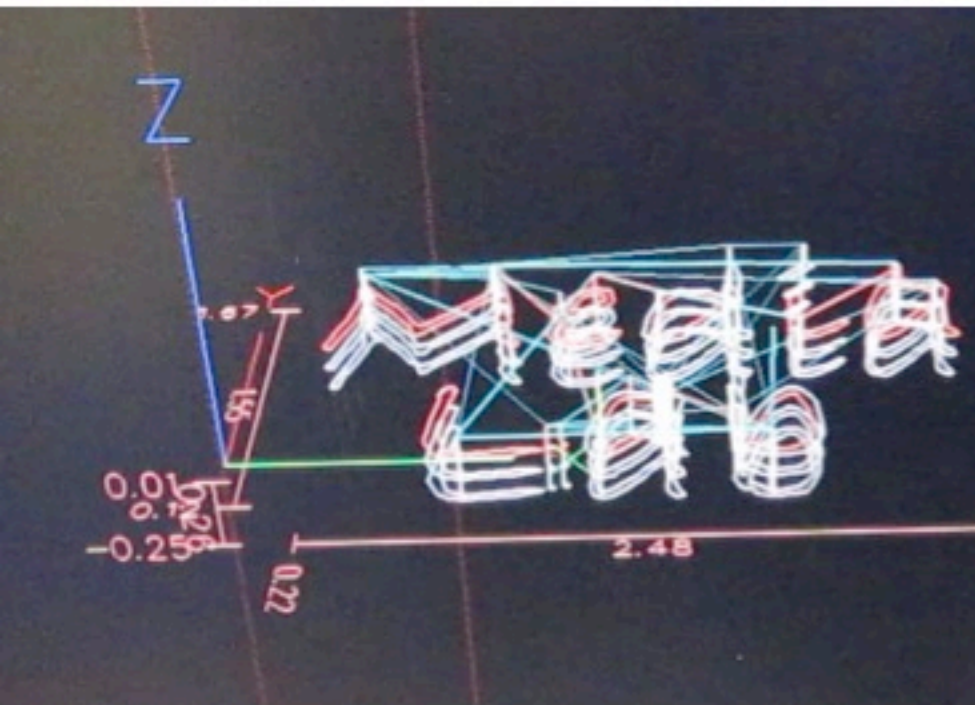
Overview

MTM "Little John" is a multi-purpose mid-size rapid prototyping machine that which has the goal of being a personal fabricator capable of performing a variety of tasks (3D printing, milling, scanning, vinyl cutting, etc.) at a price point in the hundreds rather than thousands of dollars.



Open-Source Plans (http://mtm.cba.mit.edu/machines/mtm_lj/Site/MTM_Little_John.html)

All the MTM-LJ parts are currently using two 4' x 4' x 1" sheets. Parts layout is using spacing for cutting with a 0.25" straight end-mill. Pilot holes should be cut first using a 0.125" straight end-mill, see Fabrication section for detailed screenshots. To make tool-path generation the DXF & Rhino files below are using layers.



Specifications / Key Features:

Dimensions: 2'x2'x14.5"

Working envelope: 9"x18"x5.5"

Interchangeable tool interface, multiple heads

I/O Networked motor control (unipolar+bipolar support)

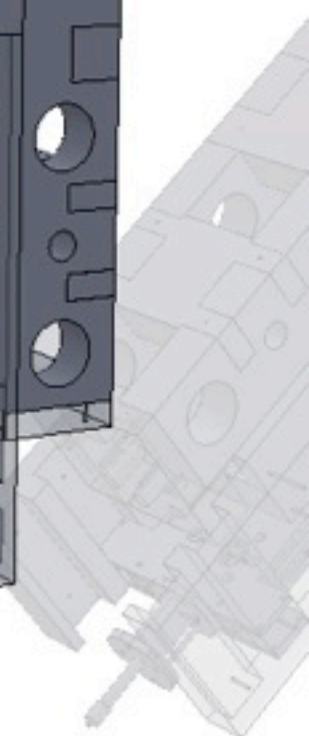
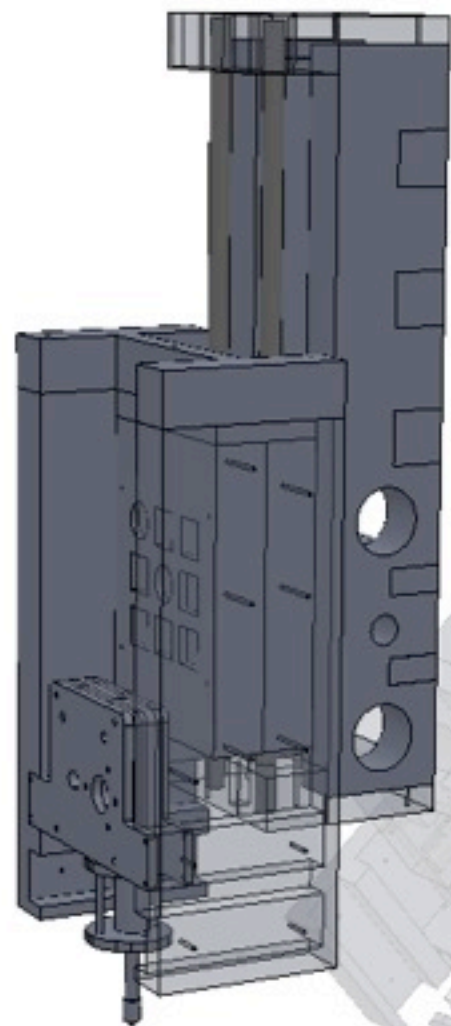
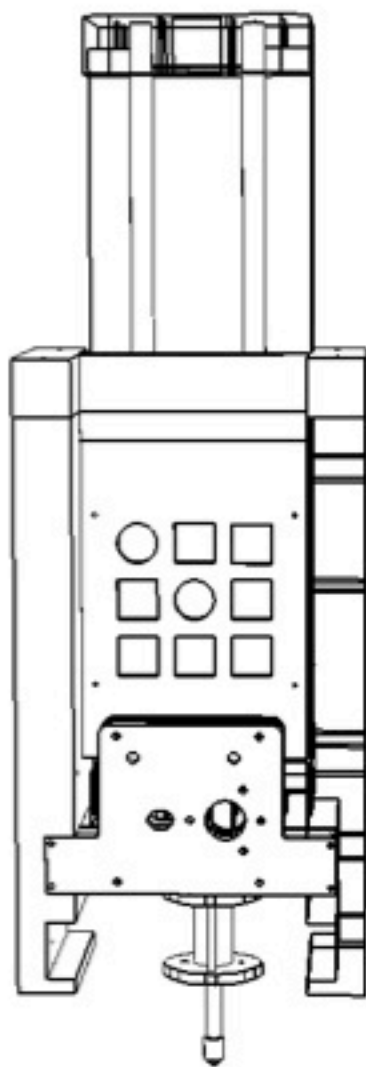
Open-source H/W + S/W Linux RT + EMC2

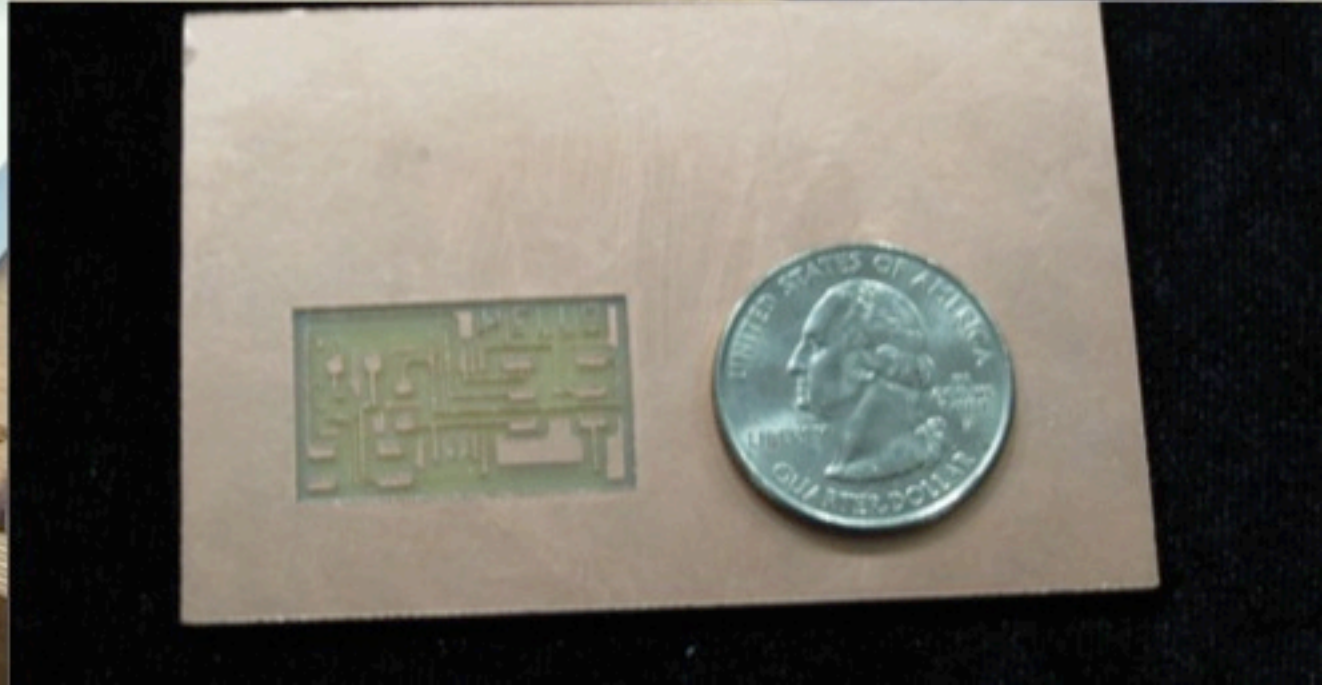
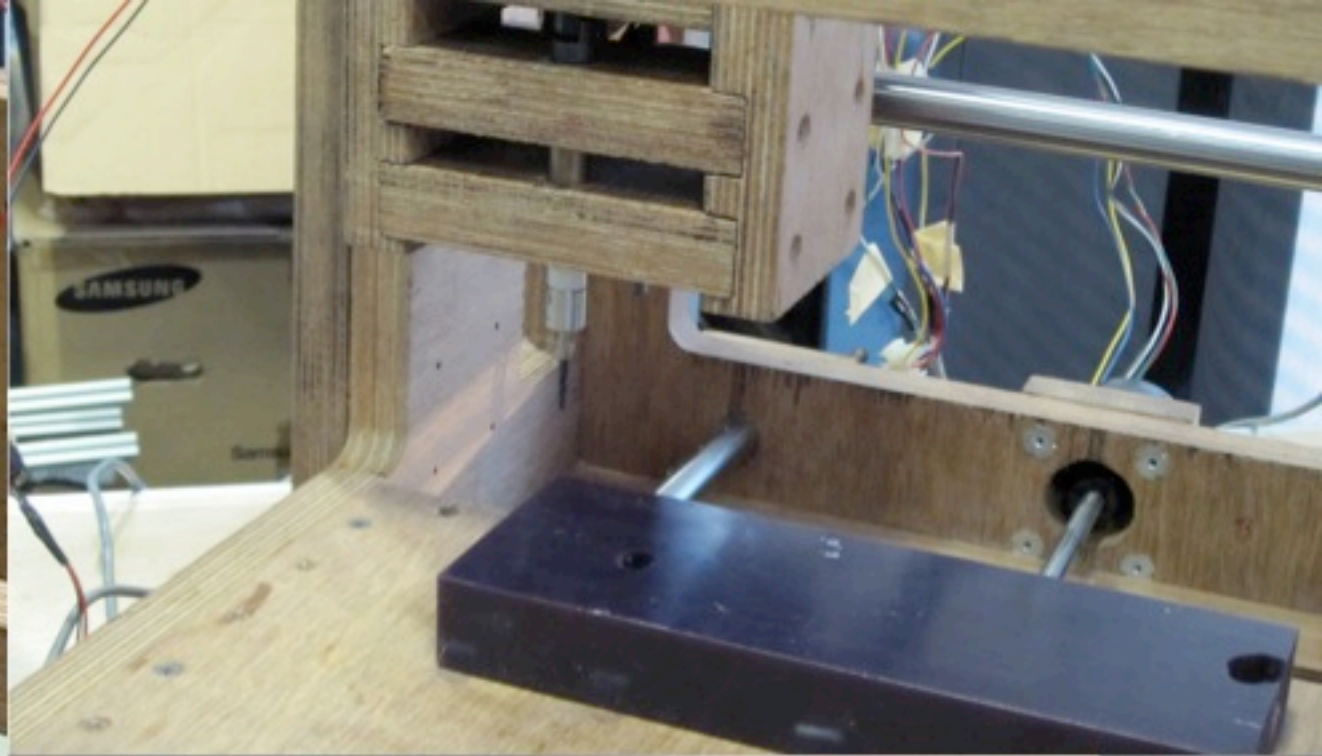
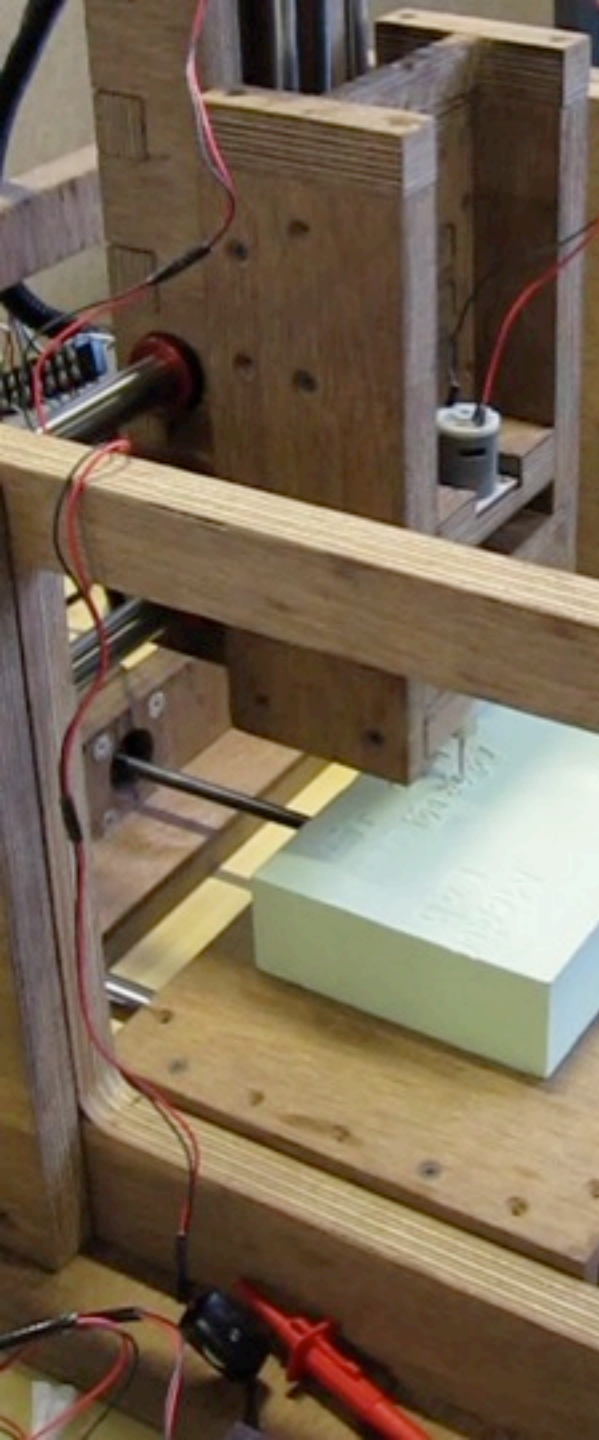


Multifab Toolinterface

MTM Little John tool interface is designed to support multiple tools-heads. Example tools can be a combination of plastic extruders, printing/plotting, milling, scanning.

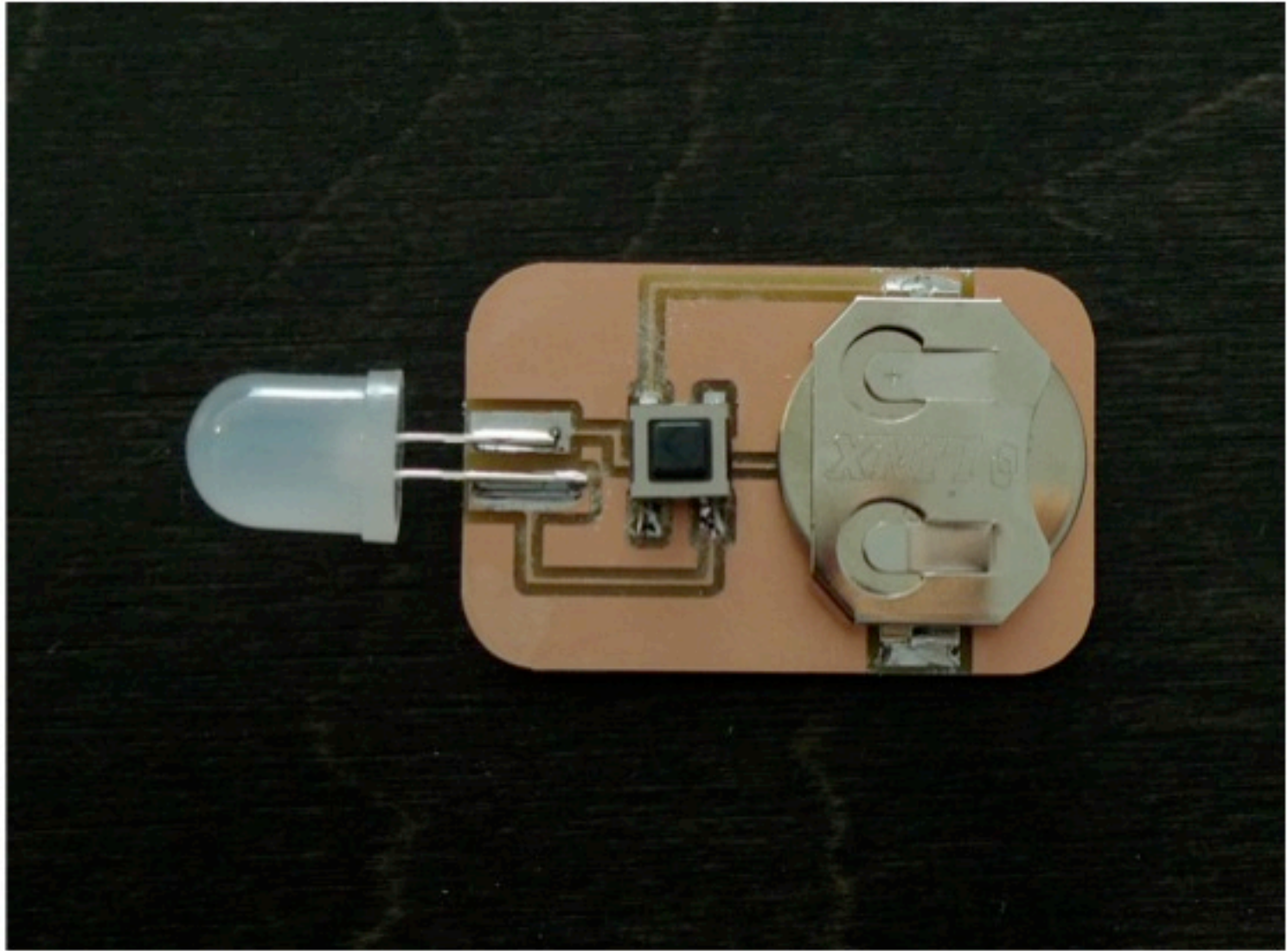
Plastruder

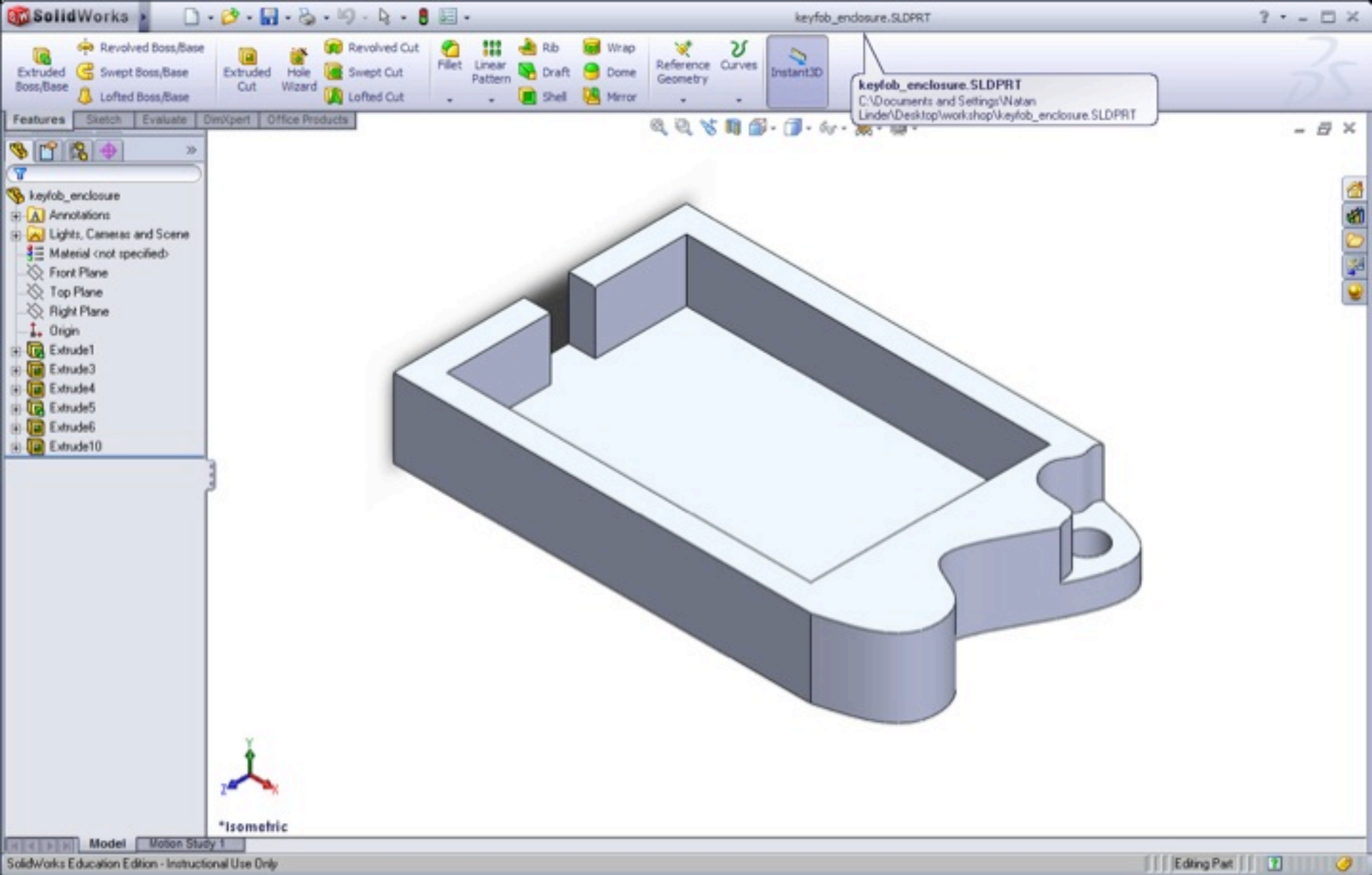




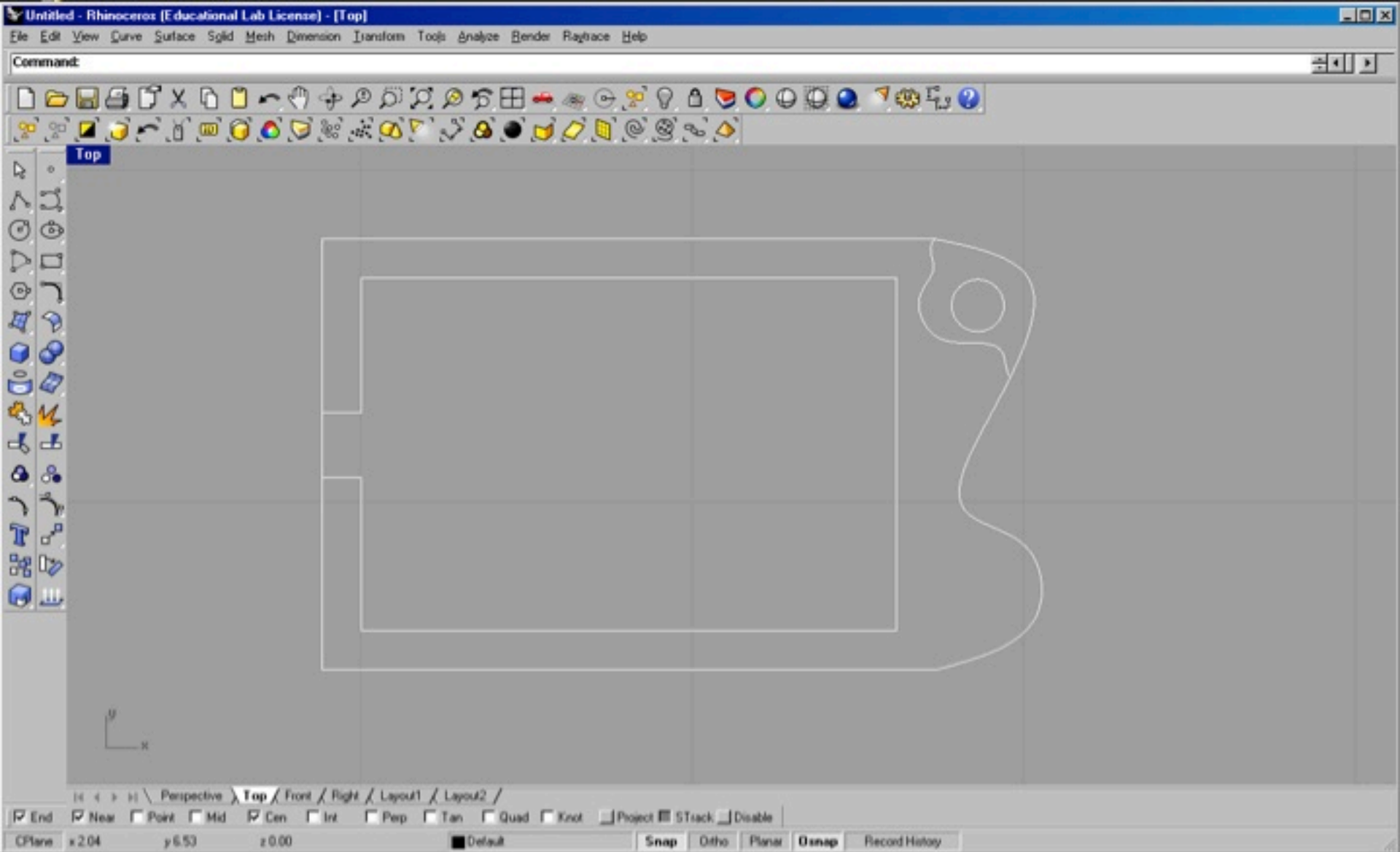
How make something with MTMs

Keychain Flashlight

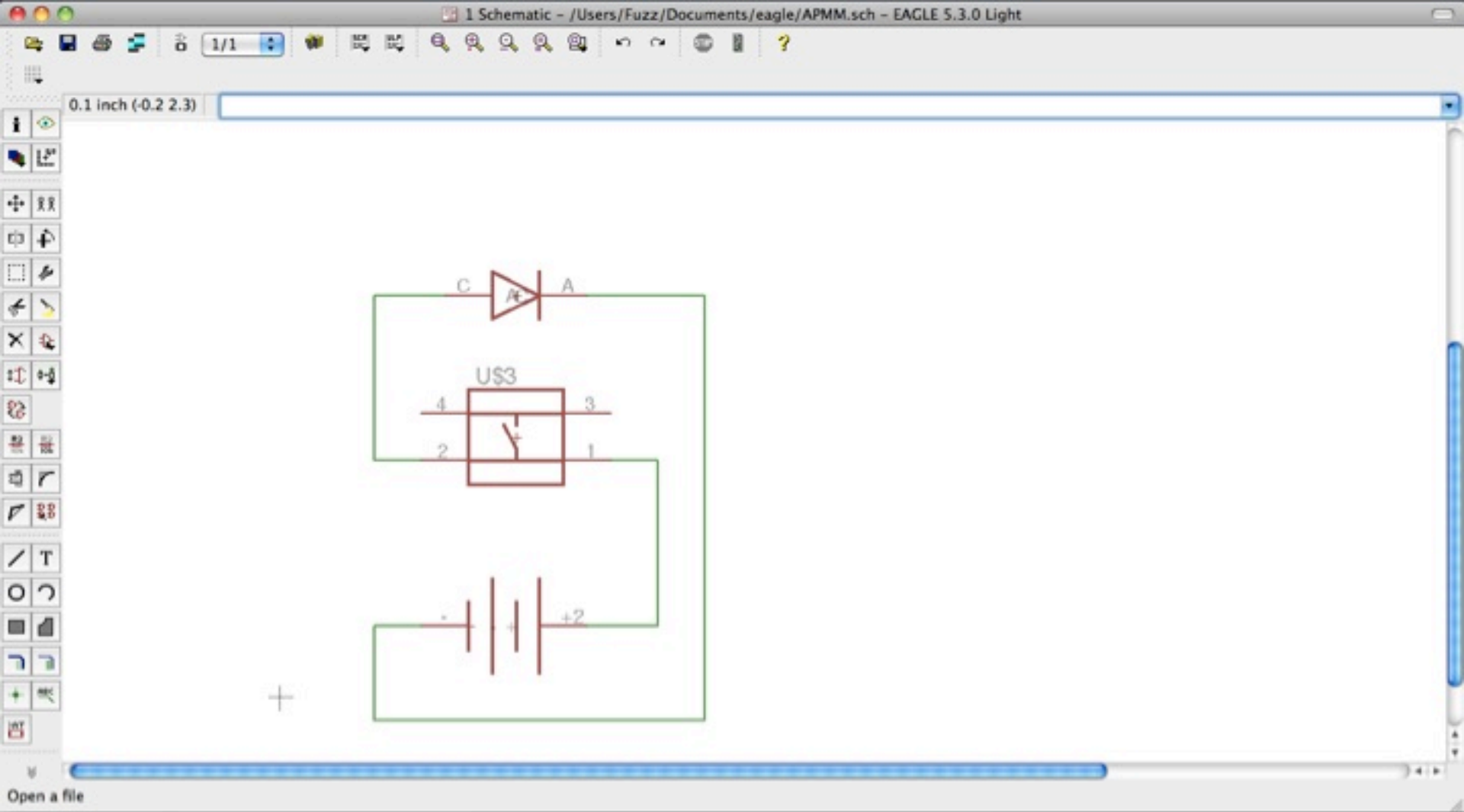




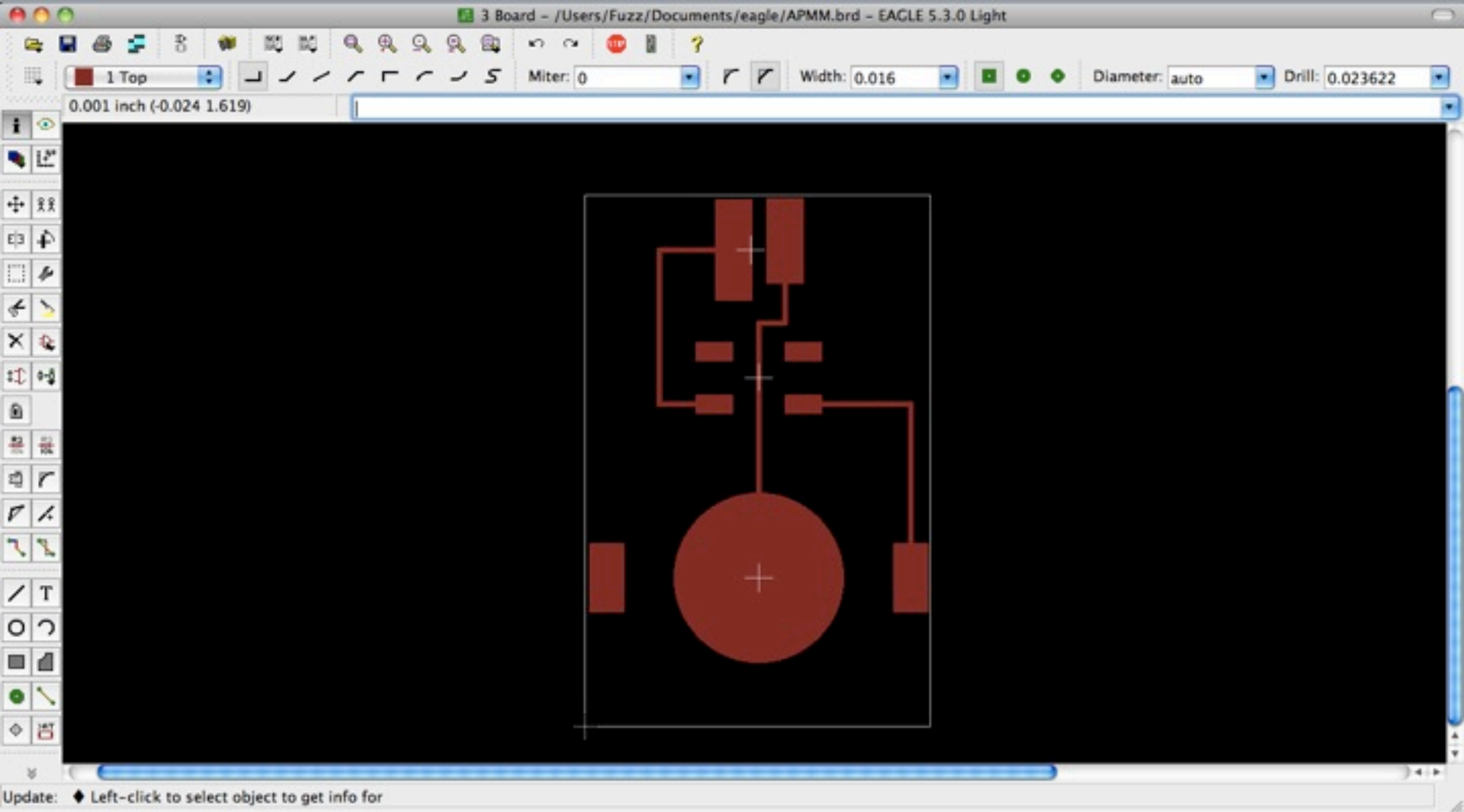
CAD – Solidworks



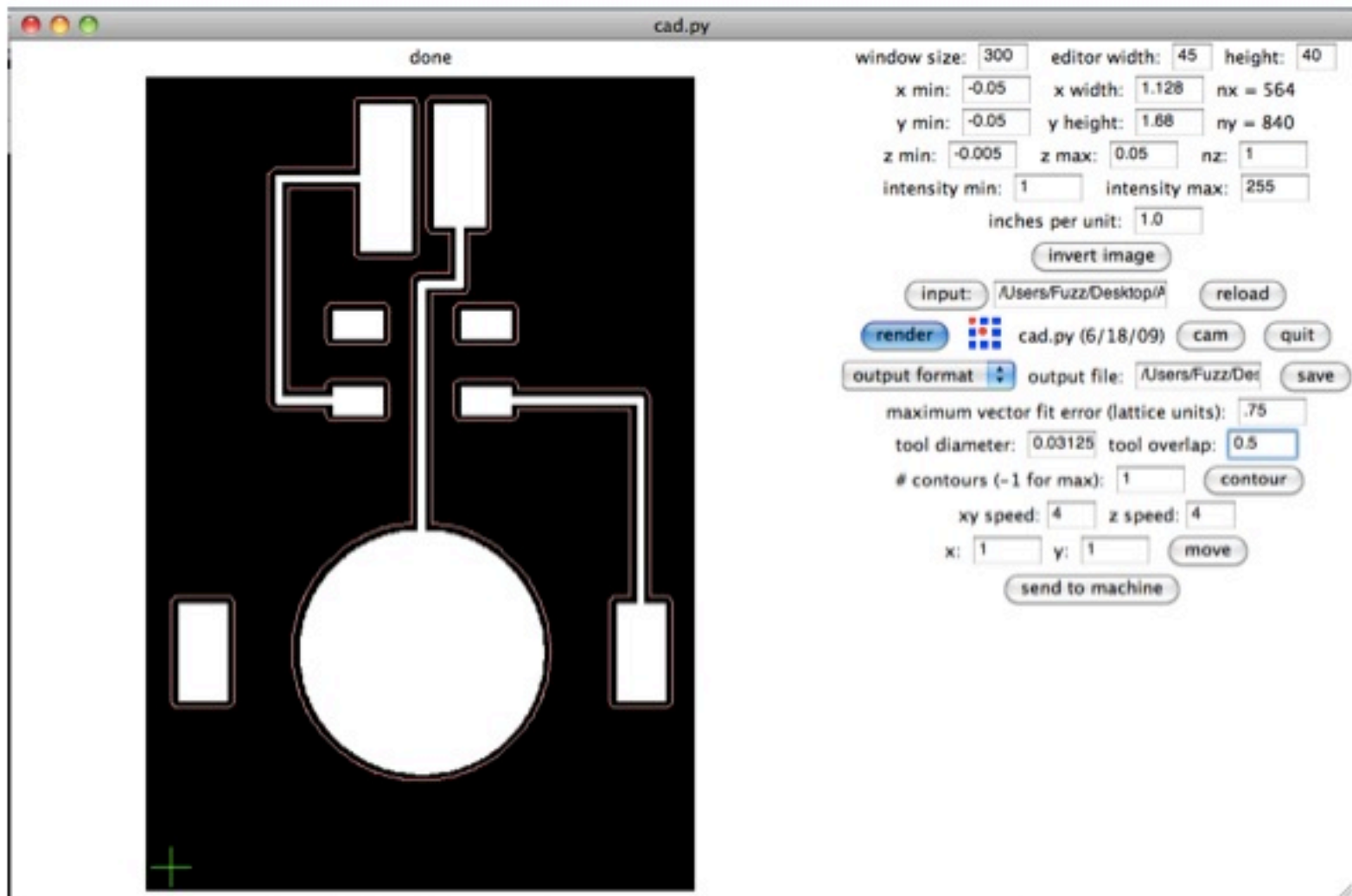
Top projection → DXF - Rhino



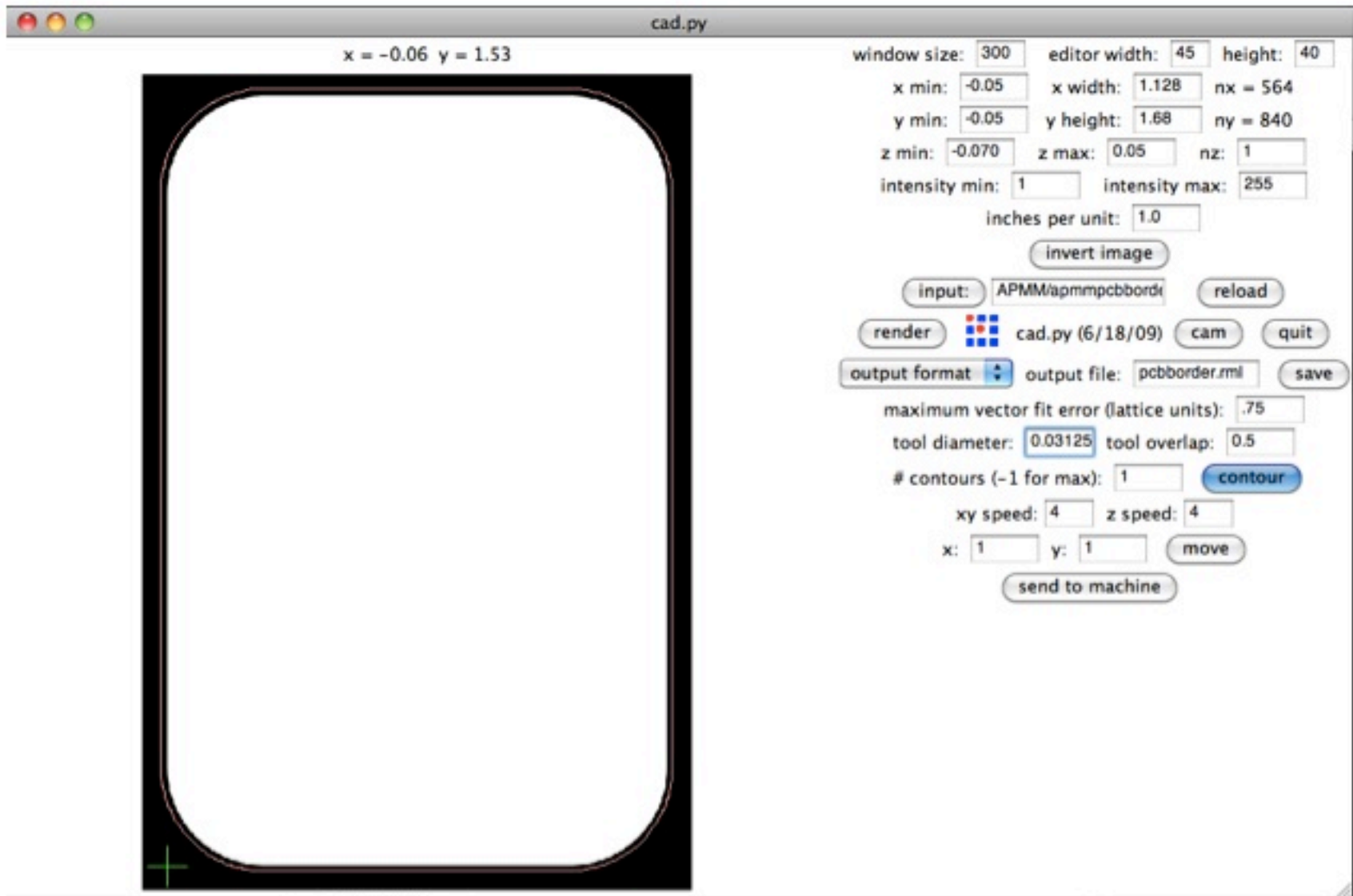
Schematics & PCB Layout – Eagle



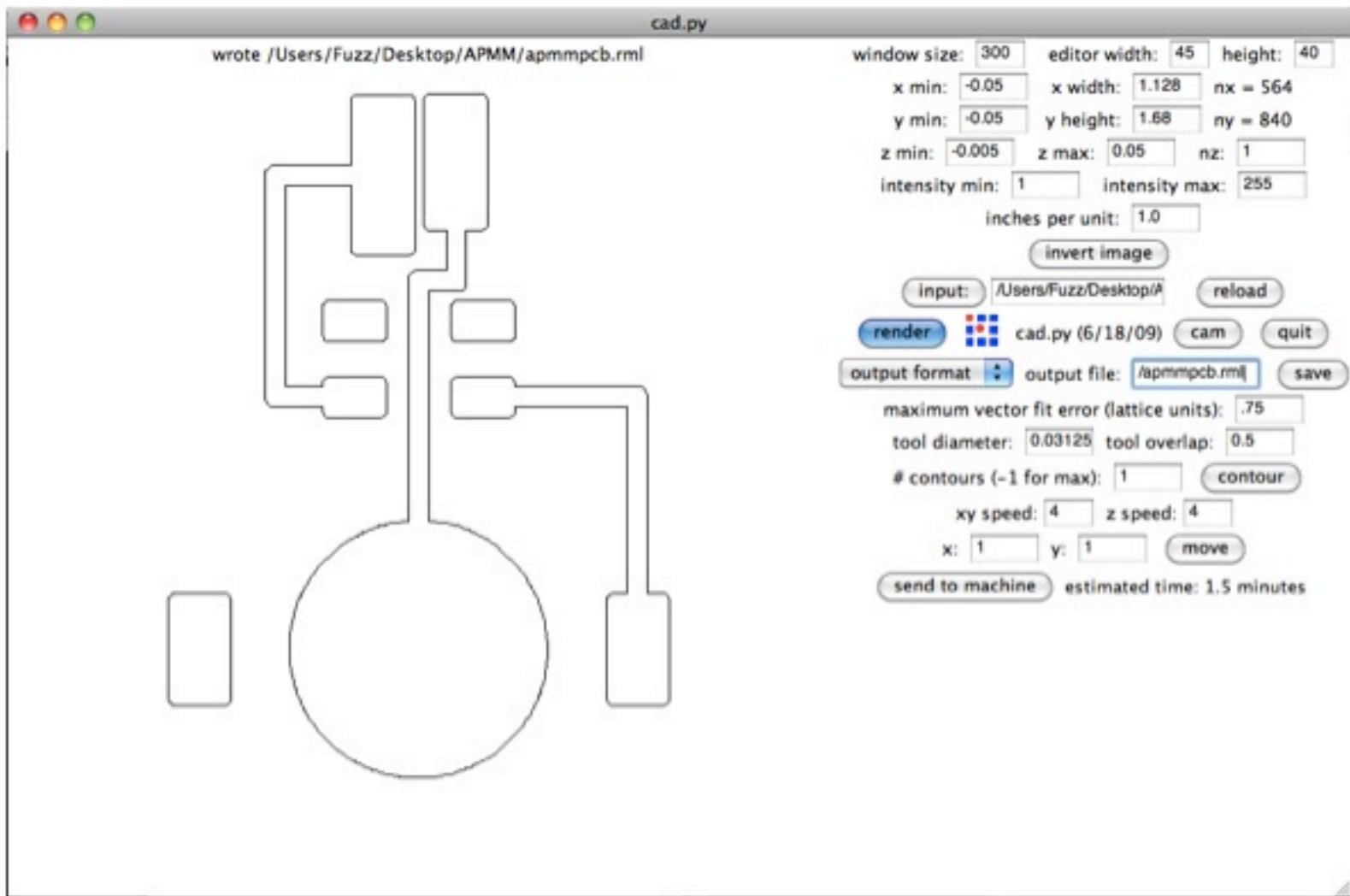
Schematics & PCB Layout – Eagle



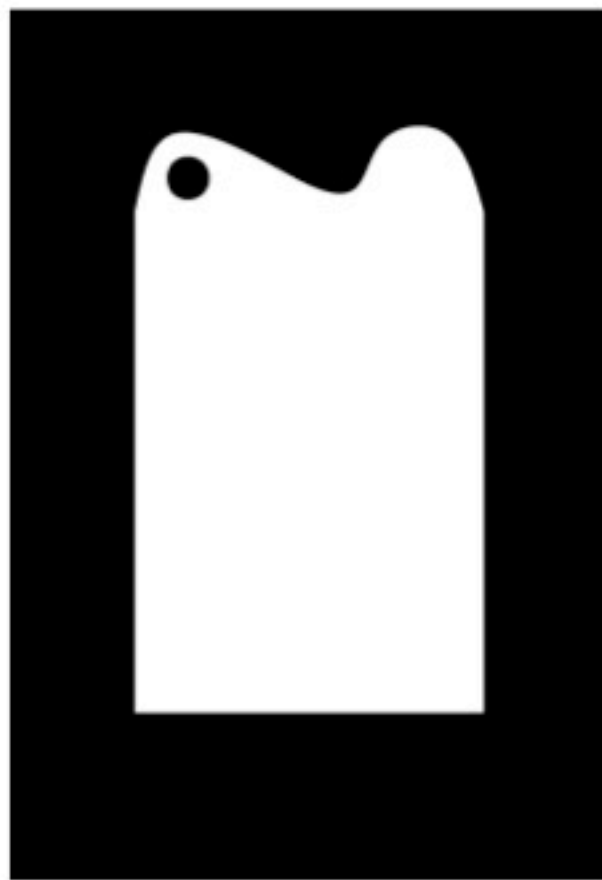
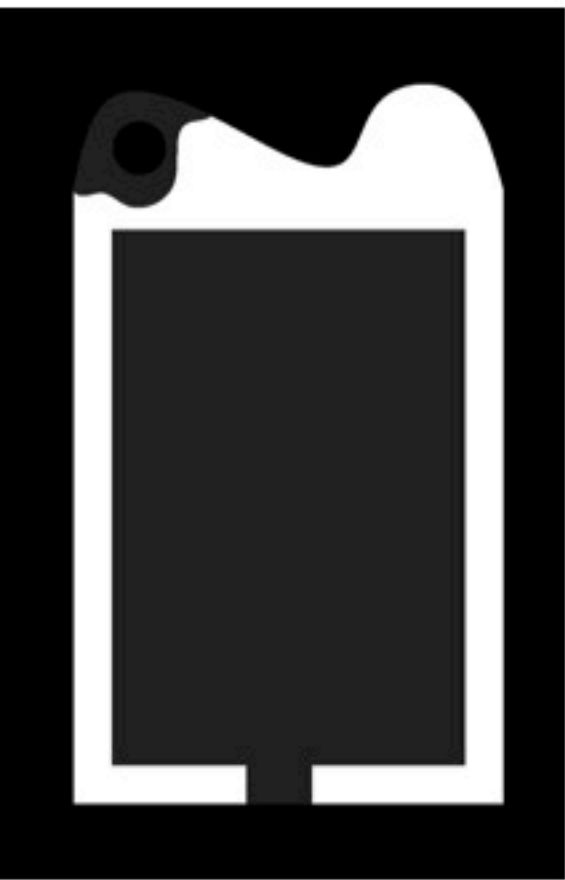
Cad.py – PCB layout



Cad.py – Border layout



Cad.py – Toolpath



Keyfob enclosure toolpath

File Machine View

Manual Control [F3] MDI [F5]

Axis: X Y Z

Continuous

Hold Axis Touch Off

Spindle:

Preview DRO

X: 0.0000
Y: 0.0000
Z: 0.0000
Vel: 0.0000

Feed Override: 100 %

Spindle Override: 100 %

Jog Speed: 5.8 in/min

Max Velocity: 30 in/min

```

1: T1M06
2: G30
3: F5.0000
4: S5000.0000
5: M08
6: G00Z0.0500
7: M03
8: G0X0.7250Y2.6190Z0.0500
9: G0I20.0500

```

ESTOP No tool Position: Relative Actual

```
keyfob_enclosure_ghallow1.g
Last Saved: 3/26/10 6:32:21 PM
File Path: ~/Desktop/APM1/Workshop/gcode/keyfob_enclosure_ghallow1.g

keyfob_enclosure_ghallow1.g

TIM06
G90
F5.0000
S5000.0000
M08
G00Z-0.2750
M03
G01X0.4970Y2.6130Z-0.2750
G01Z0.0100
X0.4950Y2.6110
X0.4770Y2.6110
X0.4750Y2.6090
X0.4690Y2.6090
X0.4670Y2.6070
X0.4590Y2.6070
X0.4570Y2.6050
X0.4490Y2.6050
X0.4470Y2.6030
X0.4390Y2.6030
X0.4370Y2.6010
X0.4290Y2.6010
X0.4270Y2.5990
X0.4230Y2.5990
X0.4210Y2.5970
X0.4150Y2.5970
X0.4130Y2.5950
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X0.4030Y2.5930
X0.3970Y2.5930
X0.3950Y2.5910
X0.3910Y2.5910
X0.3890Y2.5890
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X0.3810Y2.5850
X0.3750Y2.5830
X0.3730Y2.5810
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X0.3590Y2.5750
X0.3570Y2.5730
X0.3490Y2.5670
X0.3430Y2.5630
X0.3350Y2.5570
X0.3290Y2.5530
X0.3230Y2.5510
X0.3150Y2.5410
X0.3130Y2.5350
X0.3090Y2.5310
X0.3030Y2.5230
X0.2730Y2.4910
X0.4690Y2.4850
X0.4650Y2.4790

1 | (none) | Western (Mac OS Roman) | 100% (LF) |
```

gcode

DEMO